## DPM-100 Modbus ${ }^{\circledR}$ Display Instruction Manual



## 



## Modbus Display

- Modbus ${ }^{\circledR}$ RTU Master, Slave, or Snooper Mode
- Poll and Display up to 16 Process Variables
- Large 6-Digit Dual-Line Display, Red LEDs, Sunlight Readable
- 32-Point, Square Root, or Exponential Linearization
- Addition, Difference, Average, Multiplication, Division, Min, Max, Weighted Average, Ratio, Concentration, \& More
- Type 4X, NEMA 4X, IP65 Front
- Input Power Options Include 85-265 VAC or 12-24 VDC
- 2 or 4 Relays + 4-20 mA Output Options
- Multi-Pump Alternation Control
- Free USB Programming Software \& Cable*

[^0]Division of Garner Industries 7201 North 98th Street Lincoln, NE 68507-9741
(402) 434-9102

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Read complete instructions prior to installation and operation of the scanner.

## A <br> WARNING!

Risk of electric shock or personal injury. Hazardous voltages exist within enclosure. Installation and service should be performed only by trained service personnel.


## Limited Warranty

BinMaster warrants this product against defects in material or workmanship for the specified period under Specifications from the date of shipment from the factory. BinMaster's liability under this limited warranty shall not exceed the purchase value, repair, or replacement of the defective unit.

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## Introduction

The BinMaster DPM-100 Modbus ${ }^{\circledR}$ Scanner is a multi-purpose, easy-to-use digital scanner that can be programmed as a Modbus RTU Master, Slave, or Snooper. It is capable of scanning up to 16 variables generated by any Modbus device, which makes it ideal for tank level monitoring and control. Its superluminous LED digits make it easily readable in smoke, dust, fog, and even direct sunlight.

As a master, the DPM-100 reads up to 16 slave devices, scales the data from each, displays the result, and operates the internal relays and $4-20 \mathrm{~mA}$ output. The DPM-100 in Master mode is capable of polling up to 16 process variables ( PVs ); it displays all the enabled PV s in sequence, at a user programmable scan rate; it also allows other DPM-100s in Snooper mode to read any of the variables being polled by the master. As a snooper, the DPM-100 listens to the Modbus traffic and picks up a specific register or registers being polled by a master device from a specific slave device and processes the data being read. As a slave, it is controlled by a master device. The data sent to it by the master is scaled, displayed, and used to operate the relays and 4-20 mA output.

The DPM-100 is housed in a $1 / 8$ DIN panel scanner enclosure that features a NEMA 4X front panel. Data is displayed on an adjustable intensity, dual-line, six-digit display. The upper display is a 0.6 inch, sevensegment LED display, while the lower display digit height is 0.46 inches. The Super Snooper can be powered from 85-265 VAC or 12-36 VDC. It is available with up to 4 internal relays and is available with 4 additional relays and up to 8 digital inputs/outputs, as well as a dual $4-20 \mathrm{~mA}$ output expansion module, as options.

Various math functions may be applied to the Modbus including addition, difference, absolute difference, average, weighted average, multiplication, division, minimum, maximum, draw, ratio, and concentration. This is in addition to the signal input conditioning functions (linear, square root, programmable exponent, or round horizontal tank calculations). The displays, relays, and the analog outputs may be assigned to PVs or to math channels $\mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3$, or C 4 . The digital inputs/outputs can be custom-programmed for specific operations. A digital input (F4) is standard.

Free ScanView software allows a Super Snooper Modbus Scanner to be accessed with a computer. Configure multiple scanners, conveniently monitor critical information, and Datalog right from a PC with ease, further increasing plant efficiency.

## DPM-100 Modbus ${ }^{\circledR}$ Display Instruction Manual

Ordering Information
DPM-100 Model Numbers

| 85-265 VAC Power <br> Model Numbers | Reorder Number | Options Installed |
| :--- | :--- | :--- |
| PD6088-6H0-BM | $348-0029$ | No options |
| PD6088-6H2-BM | $348-0026$ | 2 relays |
| PD6088-6H3-BM | $348-0024$ | $4-20$ mA output |
| PD6088-6H4-BM | $348-0035$ | 4 relays |
| PD6088-6H5-BM | $348-0027$ | 2 relays \& 4-20 mA output |
| PD6088-6H7-BM | $348-0025$ | 4 relays \& 4-20 mA output |
| 12-24 VDC Power |  |  |
| Model Numbers | Reorder Number | Options Installed |
| PD6088-7H0-BM | $348-0028$ | No options |
| PD6088-7H2-BM | $348-0031$ | 2 relays |
| PD6088-7H3-BM | $348-0032$ | $4-20$ mA output |
| PD6088-7H4-BM | $348-0036$ | 4 relays |
| PD6088-7H5-BM | $348-0033$ | 2 relays \& 4-20 mA output |
| PD6088-7H7-BM | $348-0034$ | 4 relays \& 4-20 mA output |

Accessories

| Model | Description |
| :--- | :--- |
| PDA1002 | DIN rail mounting kit for two expansion modules |
| PDA1004 | 4 SPST (Form A) relays |
| PDA1011 | Dual 4-20 mA expansion module |
| PDA1044 | 4 digital inputs \& 4 digital outputs (2 may be connected) |
| PDA1485 | RS-485 serial adapter - (Included with DPM-100) |
| PDA7485-I | RS-232 to RS-422/485 isolated converter |
| PDA7485-N | RS-232 to RS-422/485 non-isolated converter |
| PDA8485-I | USB to RS-422/485 isolated converter |
| PDA8485-N | USB to RS-422/485 non-isolated converter |
| PDX6901 | Suppressor (snubber): $0.01 \mu \mathrm{~F} / 470 \Omega, 250$ VAC |

Manufactured by Precision Digital Corporation, 233 South St, Hopkinton MA 01748 USA

## Specifications

Except where noted all specifications apply to operation at $+25^{\circ} \mathrm{C}$.

| Operating Modes |  |
| :--- | :--- |
| Master | Processes data read from Modbus RTU <br> slave devices. It polls up to 16 process <br> variables from 1 to 16 slave devices. The <br> Master is capable of scanning the selected <br>  <br>  <br>  <br>  <br> PVs, scaling the data, triggering relays, <br> performing math operations, and driving the <br> analog outputs. |
| Listens to the Modbus traffic and picks up a <br> specific register or registers being polled by <br> a master device from a specific slave device <br> and processes the data being read. The <br> Snooper mode handles the data the same <br> way as the Master. |  |
|  | Processes data sent to it from a Modbus <br> RTU master device. |
| Slave | Note: The relays and the 4-20 mA outputs <br> are functional in all modes. |
| Master \& Snooper Settings |  |


| Communication Break | Displays "brERH" after the Master has polled the slave device 3 times and the response timeout has elapsed. The Snooper and Slave modes go into break condition after no new data is received within the response timeout window. Relays can be programmed to go on, off, or ignore the break condition. The analog outputs can be setup to generate a fixed mA current when a break condition is detected. |
| :---: | :---: |
| PV Settings |  |
| Tag \& Units | 6-character, independent tag and units for each PV and math channel |
| PV Format | Decimal format (default) or FT \& IN, $1 / 8$ th or $1 / 16$ th; decimal format may be selected for line 2 indication. |
| Display Decimal Point | Up to five decimal places or none: d.ddddd, dd.dddd, ddd.ddd, dddd.dd, ddddd.d, or dddddd |
| Float Decimal Point | Select the number of decimals to use for the floating point data expected from the slave or master device (this is independent from the display decimal point selection). |
| PV \& Math Scaling | All PVs and math channels may be scaled to represent the input data in any engineering unit. <br> Example: Level transmitter = 999.999 inches; to display in Ft-In-1/16 ${ }^{\text {th }}$ scale input 2 to display $83 \mathrm{Ft}-4 \mathrm{In}-0 / 16^{\text {th }}$. |

## Display Settings

| Scan Mode | Automatic: 1.0 to 99.9 sec <br> Manual: Front panel or digital inputs <br> Go on alarm: Continues scanning after an alarm is detected <br> Stop on alarm: Goes to the alarmed PV and stops scanning; press Scan to resume scanning. |
| :---: | :---: |
| Display Scan Rate | Master/Snooper: 1 PV/second to one PV every 99.9 seconds <br> Slave: Dependent on master device (e.g. PLC) <br> Note: The display scan rate is independent of the poll time. |
| Display Assignment | Display line 1 may be assigned to PV (process values), Ch-C (math channel), PV \& units, tag \& PV, tag-PV-units, C \& units, tag-C-unit, Set point 1-8, max/min PV, $\max / \min \mathrm{C}$. <br> Line 2 may be assigned to all of the above, tag, tag \& units, or off. <br> The tag and units are displayed alternately for 2 sec max, when selected. <br> Different tags \& PVs may be selected to display on line 1 and 2 at the same time. |

## Math Functions

| Name | Math Operation (Examples) ( $\mathrm{P}=$ Adder, $\mathrm{F}=$ Factor) | Setting |
| :---: | :---: | :---: |
| Addition | (PV1+PV2+P)*F | 5un7 |
| Difference | (PV1-PV2+P)*F | dif |
| Absolute difference | ((Abs(PV1-PV2)+P)*F | d IFRb5 |
| Average | $(((P V 1+P V 2) / 2)+\mathrm{P})^{*} \mathrm{~F}$ | RULS |
| Multiplication | $((\mathrm{PV} 1 * \mathrm{PV} 2)+\mathrm{P})^{*} \mathrm{~F}$ | meult |
| Division | $((\mathrm{PV} 1 / \mathrm{PV} 2)+\mathrm{P})^{*} \mathrm{~F}$ | dUdE |
| Max PV | Max value of all selected PVs | H,-PU |
| Min PV | Min value of all selected PVs | Lo-PU |
| Draw | ((PV1/PV2)-1)*F | drfus |
| Weighted average | ((PV2-PV1)*F)+PV1 | uTRUT |
| Ratio | (PV1/PV2)*F | rRt io |
| Concentration | (PV1/(PV1+PV2))*F | ConcEn |
| Math 2 | Math on other math channels | nาRth2 |
| Programmable Constants | Constant F (Factor): 0.001 to 999.999, default: 1.000 | $\begin{aligned} & 99.999, \\ & 999, \end{aligned}$ |

Serial Communications

| Scanner Id | $1-247$ (Scanner Modbus address) |
| :--- | :--- |
| Baud Rate | $300-19,200$ bps |
| Transmit Programmable 0 to 4999 ms <br> Time Delay <br> This is the time the scanner will wait for a <br> slave to respond before sending another <br> request on the bus. This value should be <br> greater than 100 ms to avoid collisions on <br> the bus. <br> Data 8 bits (1 start bit, 1 or 2 stop bits) <br> Parity Even, Odd, or None with 1 or 2 stop bits <br> Byte-To-Byte <br> Timeout $0.01-2.54$ second <br> Turn Around <br> Delay Less than 2 ms (fixed) |  |

Note: Refer to the Scanner Modbus Register Tables located at www.binmaster.com.

## General

| Input/output | Modbus RTU over RS-485 |
| :--- | :--- |
| Display | Line 1:0.60" (15 mm) high, red LEDs <br> Line 2: 0.46" (12 mm) high, red LEDs <br> 6 digits each (-99999 to 999999), with lead <br> zero blanking |
| Display <br> Intensity | Eight user selectable intensity levels |
| Overrange | Values greater than 999999 cause the <br> display to flash 999999 |
| Underrange | Values less than -99999 cause the display <br> to flash -99999 |
| Programming <br> Methods | Four front panel buttons, digital inputs, PC <br> and ScanView software, Modbus registers, or <br> cloning using Copy function. |


| Max/Min <br> Display | Max/min readings are stored until reset by <br> the user or when power to the scanner is <br> turned off. User can reset by front panel <br> pushbuttons, digital input, or via Modbus <br> registers. |
| :--- | :--- |
| Password | Three programmable passwords restrict <br> modification of programmed settings. |
|  | Pass 1: Allows use of function keys and <br> digital inputs <br> Pass 2: Allows use of function keys, digital <br> inputs and editing set/reset points <br> Pass 3: Restricts all programming, function <br> keys, and digital inputs. |
| F4 Digital Input | 50k ohm pull-up to 3.3 VDC. <br> Connect normally open contacts across F4 <br> to COM. |
| F4 Digital Input | Logic High: 3 to 5 VDC <br> Logic Low: 0 to 1.25 VDC |
| Logic Levels |  |


| Rating | 2 or 4 SPDT (Form C) internal and/or 4 SPST (Form A) external; rated 3 A @ 30 VDC and 125/250 VAC resistive load; 1/14 HP ( $\approx 50$ W) @ 125/250 VAC for inductive loads |
| :---: | :---: |
| Noise <br> Suppression | Noise suppression is recommended for each relay contact switching inductive loads. |
| Electrical Noise Suppression | A suppressor (snubber) should be connected to each relay contact switching inductive loads to prevent disruption to the microprocessor's operation. <br> Recommended suppressor value: $0.01 \mu \mathrm{~F} / 470 \Omega$, 250 VAC (PDX6901). |
| Deadband | 0-100\% of span, user programmable |
| High Or Low Alarm | User may program any alarm for high or low trip point. Unused alarm LEDs and relays may be disabled (turn off). |
| Relay Operation | Automatic (non-latching) <br> Latching (requires manual acknowledge) <br> Sampling (based on time) <br> Pump alternation control (2 to 8 relays) <br> Off (disable unused relays and enable <br> Interlock feature) <br> Manual on/off control mode |
| Relay Reset | User selectable via front panel buttons, digital inputs, or PC |
|  | 1. Automatic reset only (non-latching), when the input passes the reset point. <br> 2. Automatic + manual reset at any time (non-latching) <br> 3. Manual reset only, at any time (latching) <br> 4. Manual reset only after alarm condition has cleared (L) <br> Note: Front panel button or digital input may be assigned to acknowledge relays programmed for manual reset. |
| Time Delay | 0 to 999.9 seconds, on \& off relay time delays. Programmable and independent for each relay |
| Fail-Safe Operation | Programmable and independent for each relay. <br> Note: Relay coil is energized in non-alarm condition. In case of power failure, relay will go to alarm state. |
| Auto Initialization | When power is applied to the scanner, relays will reflect the state of the input to the scanner. |

Isolated 4-20 mA Transmitter Output

| Output Source | PV1-16, math channels C1-4, set points 1-8, or manual control mode |
| :---: | :---: |
| Scaling Range | 1.000 to 23.000 mA for any display range |
| Calibration | Factory calibrated: 4.000 to $20.000=4-20$ mA output |
| Analog Out Programming | 23.000 mA maximum for all parameters: Overrange, underrange, max, min, and break |
| Communications Break | Programmable mA output when a slave device does not reply within the response timeout. |
| Accuracy | $\pm 0.1 \%$ of span $\pm 0.004 \mathrm{~mA}$ |
| Temperature Drift | $0.4 \mu \mathrm{~A} /{ }^{\circ} \mathrm{C}$ max from 0 to $65^{\circ} \mathrm{C}$ ambient, $0.8 \mu \mathrm{~A} /{ }^{\circ} \mathrm{C}$ max from -40 to $0^{\circ} \mathrm{C}$ ambient. Note: Analog output drift is separate from input drift. |
| Isolated <br> Transmitter Power Supply | Terminals I+ \& R: $24 \mathrm{VDC} \pm 10 \%$. May be used to power the 4-20 mA output or other devices. Refer to Figure 4 on page 13 and Figure 12 on page 17. All models rated @ 40 mA max. |
| External Loop Power Supply | 35 VDC maximum |
| Output Loop <br> Resistance | Power supply Minimum Maximum |
|  | $24 \mathrm{VDC} \quad 10 \Omega \quad 700 \Omega$ |
|  | 35 VDC <br> (external) $100 \Omega$ $1200 \Omega$ |

## MeterView Pro

| System <br> Requirements | Microsoft $^{\circledR}$ Windows $^{\circledR}$ XP/Vista/7/8/10 |
| :--- | :--- |
| Communica- <br> tions | USB 2.0 (Standard USB A to Micro USB B) |

## Compliance Information

Safety

| UL \& c-UL LISTED | USA \& Canada <br> UL 508 Industrial Control Equipment |
| :--- | :--- |
| UL FILE NUMBER | E160849 |
| FRONT PANEL | UL Type 4X, NEMA 4X, IP65; panel gasket provided |
| LOW VOLTAGE | EN 61010-1:2010 |
| DIRECTIVE | Safety requirements for measurement, control, and laboratory use |

## Electromagnetic Compatibility

| EMISSIONS | $\begin{aligned} & \text { EN 55022:2010 } \\ & \text { Class A ITE emissions requirements } \end{aligned}$ |
| :---: | :---: |
| Radiated Emissions | Class A |
| AC Mains Conducted Emissions | Class A |
| IMMUNITY | EN 61326-1:2013 <br> Measurement, control, and laboratory equipment <br> EN 61000-6-2:2005 <br> EMC heavy industrial generic immunity standard |
| RFI - Amplitude Modulated | $80-1000 \mathrm{MHz} 10 \mathrm{~V} / \mathrm{m} 80 \% \mathrm{AM}(1 \mathrm{kHz})$ <br> 1.4-2.0 GHz $3 \mathrm{~V} / \mathrm{m} 80 \% \mathrm{AM}(1 \mathrm{kHz})$ <br> 2.0-2.7 GHz $1 \mathrm{~V} / \mathrm{m} 80 \% \mathrm{AM}(1 \mathrm{kHz})$ |
| Electrical Fast Transients | $\pm 2 \mathrm{kV}$ AC mains, $\pm 1 \mathrm{kV}$ other |
| Electrostatic Discharge | $\pm 4 \mathrm{kV}$ contact, $\pm 8 \mathrm{kV}$ air |
| RFI - Conducted | 10V, 0.15-80 MHz, 1kHz 80\% AM |
| AC Surge | $\pm 2 \mathrm{kV}$ Common, $\pm 1 \mathrm{kV}$ Differential |
| Surge | 1KV (CM) |
| Power-Frequency Magnetic Field | $30 \mathrm{~A} / \mathrm{m} 70 \% \mathrm{~V}$ for 0.5 period |
| Voltage Dips | $40 \% \mathrm{~V}$ for 5 \& 50 periods $70 \% \mathrm{~V}$ for 25 periods |
| Voltage Interruptions | $<5 \% \mathrm{~V}$ for 250 periods |

Note:
Testing was conducted on DPM-100 meters installed through the covers of grounded metal enclosures with cable shields grounded at the point of entry representing installations designed to optimize EMC performance.

## Safety Information

| Read complete instructions prior to |
| :---: | :---: | :---: |
| installation and operation of the |
| scanner. |

## Installation

There is no need to remove the scanner from its case to complete the installation, wiring, and setup of the scanner.

## Unpacking

Remove the scanner from box. Inspect the packaging and contents for damage. Report damages, if any, to the carrier. If any part is missing or the scanner malfunctions, please contact your supplier or the factory for assistance.

## Panel Mounting

- Prepare a standard $1 / 8$ DIN panel cutout $-3.622^{\prime \prime} \times 1.772^{\prime \prime}(92 \mathrm{~mm} \times 45 \mathrm{~mm})$. Refer to Figure 1 for more details.
- Clearance: allow at least 6" (152 mm) behind the panel for wiring.
- Panel thickness: 0.04" - 0.25" (1.0 mm - 6.4 mm ).

Recommended minimum panel thickness to maintain Type 4X rating: 0.06" ( 1.5 mm ) steel panel, 0.16 " ( 4.1 mm ) plastic panel.

- Remove the two mounting brackets provided with the scanner (back-off the two screws so that there is $1 / 4 "(6.4 \mathrm{~mm})$ or less through the bracket. Slide the bracket toward the front of the case and remove).
- Insert scanner into the panel cutout.
- Install mounting brackets and tighten the screws against the panel. To achieve a proper seal, tighten the mounting bracket screws evenly until scanner is snug to the panel along its short side. DO NOT OVER TIGHTEN, as the rear of the panel may become damaged.


Figure 1. 1/8 DIN Panel Cutout Dimensions \& Panel Mounting Details

Mounting Dimensions
1.76"


Figure 2. Scanner Dimensions - Side View


Figure 3. Scanner Dimensions - Top View

## Connections

All connections are made to removable screw terminal connectors located at the rear of the scanner.
Use copper wire with $60^{\circ} \mathrm{C}$ or $60 / 75^{\circ} \mathrm{C}$ insulation for all line voltage connections. Observe all safety regulations. Electrical wiring should be performed in accordance with all applicable national, state, and local codes to prevent damage to the scanner and ensure personnel safety.

```

\section*{Connectors Labeling}

The connectors' label, affixed to the scanner, shows the location of all connectors available with requested configuration.

Do not connect any equipment other than BinMaster's expansion modules, cables, or scanners to the RJ45 M-LINK connector. Otherwise damage will occur to the equipment and the scanner.


Figure 4. Connector Labeling for Fully Loaded DPM-100

\section*{Power Connections}

Power connections are made to a two-terminal connector labeled POWER on the back of the scanner. The scanner will operate regardless of DC polarity connection. The + and - symbols are only a suggested wiring convention.


Required External Fuse:
5 A max, 250 V Slow Blow
Figure 5. Power Connections

\section*{Serial Communications Connection}

Serial communications connection is made to an RJ45 connector labeled M-LINK on the back of the scanner. The Modbus Scanner uses the PDA1485 RS-485 adapter to interface with other Modbus devices and the PDA8485 RS-485 to USB converter or PDA7485 RS-232 to RS-485 converter to connect to a PC. The same port is used for interfacing with all expansion modules (e.g. external relays, digital I/O).

DPM-100 Master as local display


Figure 6. Serial Communications Connections

\section*{Serial Communications Connections Table}

The table below shows the terminal connections for 3-wire RS-485 devices.
\begin{tabular}{|c|c|c|c|c|}
\hline \begin{tabular}{l}
DPM-100 \\
Master
\end{tabular} & \begin{tabular}{l}
DPM-100 \\
Snooper
\end{tabular} & \begin{tabular}{l}
PC \\
Connection
\end{tabular} & Modbus Slave Meter & Modbus Level Gauge \\
\hline \[
\begin{gathered}
\text { PDA1485 } \\
\text { RS-485 Adapter }
\end{gathered}
\] & \[
\begin{gathered}
\text { PDA1485 } \\
\text { RS-485 Adapter }
\end{gathered}
\] & \[
\begin{gathered}
\text { PDA8485 } \\
\text { RS- } 485 \text { to USB }
\end{gathered}
\] & RS-485 & RS-485 \\
\hline \(\stackrel{1}{\underline{1}}\) & \(\stackrel{1}{1}\) & \(\stackrel{1}{\underline{1}}\) & G & GND \\
\hline \(\overline{\mathrm{D}}\) - \(\overline{\mathrm{DO}}\) & \(\overline{\mathrm{D}}\) - \(\overline{\mathrm{DO}}\) & \(\overline{\mathrm{D}}\) - \(\overline{\mathrm{DO}}\) & D- & A (-) \\
\hline DI-DO & DI-DO & DI-DO & D+ & B (+) \\
\hline
\end{tabular}

\section*{Three Wire Connections}

In order to wire the 5 pins for use as a 3-wire half-duplex RS-485 connection, it is necessary to create a jumper connection between DI - DO and DI- - DO- as shown below.


Figure 7. Three-Wire RS485 Connection

\section*{F4 Digital Input Connections}

A digital input, F 4 , is standard on the scanner. This digital input connected with a normally open closure across F4 and COM, or with an active low signal applied to F4.


Figure 8. F4 Digital Input Connections

\section*{Relay Connections}

Relay connections are made to two six-terminal connectors labeled RELAY1 - RELAY4 on the back of the scanner. Each relay's C terminal is common only to the normally open (NO) and normally closed (NC) contacts of the corresponding relay. The relays' \(C\) terminals should not be confused with the COM (common) terminal of the INPUT SIGNAL connector.


Figure 9. Relay Connections

\section*{Switching Inductive Loads}

The use of suppressors (snubbers) is strongly recommended when switching inductive loads to prevent disrupting the microprocessor's operation. The suppressors also prolong the life of the relay contacts. Suppression can be obtained with resistor-capacitor (RC) networks assembled by the user or purchased as complete assemblies. Refer to the following circuits for RC network assembly and installation:


Figure 10. AC and DC Loads Protection

\section*{Choose \(\mathbf{R}\) and \(\mathbf{C}\) as follows:}

R: 0.5 to \(1 \Omega\) for each volt across the contacts
\(\mathrm{C}: 0.5\) to \(1 \mu \mathrm{~F}\) for each amp through closed contacts

\section*{Notes:}
1. Use capacitors rated for 250 VAC.
2. RC networks may affect load release time of solenoid loads. Check to confirm proper operation.
3. Install the RC network at the scanner's relay screw terminals. An RC network may also be installed across the load. Experiment for best results.


Use a diode with a reverse breakdown voltage two to three times the circuit voltage and forward current at least as large as the load current.

Figure 11. Low Voltage DC Loads Protection DCLoadProt

\section*{RC Networks Available from BinMaster}

RC networks are available from BinMaster and should be applied to each relay contact switching an inductive load. Part number: PDX6901.

Note: Relays are de-rated to 1/14 HP (50 watts) with an inductive load.

\section*{4-20 mA Output Connections}

Connections for the 4-20 mA transmitter output are made to the connector terminals labeled MA OUT. The 4-20 mA output may be powered internally or from an external power supply.


Figure 12. 4-20 mA Output Connections

\section*{Analog Output Transmitter Power Supply}

The internal 24 VDC power supply powering the analog output may be used to power other devices, if the analog output is not used. The \(\mathrm{I}+\) terminal is the +24 V and the R terminal is the return.

\section*{External Relay, Analog Output, \& Digital I/O Connections}

The relay, analog out, and digital I/O expansion modules PDA1004, PDA1011, and PDA1044 are connected to the scanner using a CAT5 cable provided with each module. The two RJ45 connectors on the I/O expansion modules are identical and interchangeable; they are used to connect additional modules to the system. See LIM1044, Expansion Module Instruction Manual, for details.
Note: The jumper located between the RJ45 connectors of the PDA1044 must be removed on the second digital I/O module in order for the system to recognize it as module \#2.


Warning!

Do not connect or disconnect the expansion modules with the power on! More detailed instructions are provided with each optional expansion module.

\section*{Interlock Relay Feature}

As the name implies, the interlock relay feature reassigns one, or more, alarm/control relays for use as interlock relay(s). Interlock contact(s) are wired to digital input(s) and trigger the interlock relay. This feature is enabled by configuring the relay and relative digital input(s). In one example, dry interlock contacts are connected in series to one digital input which will be used to force on (energize) the assigned interlock power relay when all interlock contacts are closed (safe). The interlock relay front panel LED flashes when locked out. The interlock relay would be wired in-series with the load (N/O contact). See below.


Interlock
Contact (Digital Input)

\(\begin{array}{cc}\text { Control } & \text { Interlock } \\ \text { Relay } & \text { Relay }\end{array}\)

Figure 13. Interlock Connections

\section*{Setup and Programming}

\section*{Overview}

There are no jumpers involved in the scanner setup procedure.
Setup and programming is done using ScanView software or through the front panel buttons.
After power and signal connections have been completed and verified, apply power to the scanner.

\section*{Front Panel Buttons and Status LED Indicators}

\begin{tabular}{|c|c|}
\hline Button Symbol & Description \\
\hline \(\stackrel{\square}{\text { MENU }}\) & Menu \\
\hline \(\underset{\text { Prev }}{ }{ }_{\text {a }}\) & PREV/Right arrow/F1 \\
\hline NEXT \({ }_{\text {F2 }}\) & NEXT/Up arrow/F2 \\
\hline \(\underset{\text { SCAN }}{ }{ }_{\text {ch }}\) & SCAN/Enter/F3 \\
\hline PREV & Go to previous PV \\
\hline NEXT & Go to next PV \\
\hline
\end{tabular}
\begin{tabular}{|l|l|}
\hline LED & Status \\
\hline \(1-8\) & Alarm 1-8 indicator \\
\hline \begin{tabular}{l}
\(1-8\) \\
M
\end{tabular} & \begin{tabular}{l} 
Flashing: Relay in manual control \\
mode
\end{tabular} \\
\hline \(1-4\) & \begin{tabular}{l} 
Flashing: Relay interlock switch \\
open
\end{tabular} \\
\hline F & Communications Fault Condition \\
\hline II PAUSE & Press SCAN to pause scanning \\
\hline PLAY & Press SCAN to resume scanning \\
\hline STOP & Stop scan on alarm \\
\hline \begin{tabular}{l} 
Note 1: F4 is a digital input. Alarms 5-8 are \\
enabled when relay expansion module installed. \\
\begin{tabular}{l} 
Note 2: LEDs for relays in manual mode flash \\
with the "M" LED every 10 seconds.
\end{tabular} \\
\hline
\end{tabular} \(\mathbf{l}\) \\
\hline
\end{tabular}
- Press the Menu button to enter or exit the Programming Mode at any time.
- Press the Right arrow button to move to the next digit during digit or decimal point programming.
- Press the Up arrow button to scroll through the menus, decimal point, or to increment a digit.
- Press the Enter button to access a menu or to accept a setting.
- Press and hold the Menu button for three seconds to access the advanced features of the scanner.
- Press the SCAN/Enter button once to pause scanning (Pause LED flashes), then press the SCAN/Enter button again to resume scanning (Play LED turns on).
- Press NEXT to go to the next PV; auto scan resumes after 10 seconds of inactivity.
- Press PREV to go to the previous PV; auto scan resumes after 10 seconds of inactivity.

\section*{Display Functions \& Messages}

The following table shows the main menu functions and messages in the order they appear in the menu.
\begin{tabular}{|c|c|c|c|c|c|}
\hline Display & Parameter & Description & Display & Parameter & Description \\
\hline nר odE & Mode & Enter Mode menu & t-rESP & Response Time & Enter the time allow \\
\hline \% RStEr & Master & Enter Master Mode & & & slave device to respond to a command. \\
\hline Puinbr & PV Number & Select PV & Snooper & Snooper & Enter Snooper Mode \\
\hline PU & PV & Select PV 1-16 & Puinbr & PV Number & Select PV \\
\hline EnRble & Enable & Enable PV & PU & PV & Select PV 1-16 \\
\hline  & Disable & Disable PV & EnRble & Enable & Enable PV \\
\hline 5LRU id & Slave ID & Enter the unique Slave ID for each PV & d.5RbL & Disable & Disable PV \\
\hline FunLod & Function Code & Enter the Function Code for each PV & 5LRLI id & Slave ID & Enter the unique Slave ID of the device to be polled by Master \\
\hline rEE.nbr & Register Number & Enter the Register Number for each PV & FunLad & Function Code & Enter the Function Code for each PV \\
\hline dRER & Data Type & Enter the Data Type for each PV & Fun 03 & Function Code 03 & Use Function Code 03 to read slave device \\
\hline \multirow[t]{2}{*}{FLont} & \multirow[t]{2}{*}{Floating Point Data Type} & \multirow[t]{2}{*}{Floating Point Data Type. Select Floating Point as the data type to be read from the slave device.} & Fun 04 & Function Code 04 & Use Function Code 04 to read slave device \\
\hline & & & Fun 55 & Function Code 65 & Use Function Code 65 to read slave device \\
\hline Short & Short Integer Data Type & Short Integer Data Type. Select Short Integer as the data type to be read from the slave device. & rEu.nbr & \begin{tabular}{l}
Register \\
Number
\end{tabular} & Enter the Register Number for each PV \\
\hline Lonis & Long Integer Data Type & \begin{tabular}{l}
the slave device. \\
Long Integer Data Type. Select Long Integer as the data type to be read from the slave device.
\end{tabular} & \[
\begin{array}{lll}
5 & d \\
5 & d \\
\hline
\end{array}
\] & Register Number Digits & Select either 5 (x0001x9999) or 6 (x00001x65536) digits for the Register Number by pressing the Right Arrow in Register Number menu. \\
\hline bimiry & Binary & Binary Data format. Select Binary format for Short or Long integers. & diftr & Data Type & Enter the Data Type for each PV \\
\hline bed & \(B C D\) & BCD Data format. Select \(B C D\) format for Short or Long integers. & FLont & Floating Point Data Type & Floating Point Data Type. Select Floating Point as the data type to be read from the slave device. \\
\hline 5 ¢fined & Signed & Signed Data. Select Signed Binary format for Short or Long integers. & \multirow[t]{2}{*}{Short} & \multirow[t]{2}{*}{Short Integer Data Type} & \multirow[t]{2}{*}{Short Integer Data Type. Select Short Integer as the data type to be read from the slave device.} \\
\hline \multirow[t]{2}{*}{un5 ind} & \multirow[t]{2}{*}{Unsigned} & \multirow[t]{2}{*}{Unsigned Data. Select Unsigned Binary format for Short or Long integers.} & & & \\
\hline & & & Lanis & Long Integer & Long Integer Data Type. \\
\hline 1234 & Byte Order & Select big-endian byte order. & & & Select Long Integer as the data type to be read from the slave device. \\
\hline 4321 & Byte Order & Select little-endian byte order. & binkry & Binary & Binary Data. Select Binary format for Short or Long \\
\hline \multirow[t]{2}{*}{2413} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select byte-swapped bigendian byte order. Not available for Short integer.} & & & integers \\
\hline & & & bod & \(B C D\) & \(B C D\) Data. Select BCD format for Short or Long \\
\hline \multirow[t]{2}{*}{3412} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select byte-swapped littleendian byte order. Not available for Short integer.} & & & integers. \\
\hline & & & 5 funed & Signed & Signed Data. Select Signed Binary format for Short or \\
\hline \multirow[t]{2}{*}{\(t-\) Poil} & \multirow[t]{2}{*}{Polling Time} & \multirow[t]{2}{*}{Enter Polling Time (the time between read commands). In other words, how often the display is updated in Master mode.} & & & Long integers. \\
\hline & & & un5 & Unsigned & Unsigned Data. Select Unsigned Binary format for Short or Long integers. \\
\hline
\end{tabular}

DPM-100 Modbus \({ }^{\circledR}\) Display Instruction Manual
\begin{tabular}{|c|c|c|c|c|c|}
\hline Display & Parameter & Description & Display & Parameter & Description \\
\hline \multirow[t]{2}{*}{1234} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select big-endian byte order.} & LRE & Tag & Tag \\
\hline & & & units & Units & Units \\
\hline 4321 & Byte Order & Select little-endian byte order. & Form 1 & Format & Format (Decimal, Eighths, or Sixteenths of an Inch) \\
\hline \multirow[t]{2}{*}{2413} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select byte-swapped bigendian byte order. Not available for Short.} & dEc & Decimal & Decimal Format \\
\hline & & & Ft in 8 & Eighths & Eighth Inch Format \\
\hline \multirow[t]{2}{*}{3412} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select byte-swapped littleendian byte order. Not available for Short.} & Ft in is & Sixteenths & Sixteenth Inch Format \\
\hline & & & dEc.Pt & Decimal Point & Decimal Point menu \\
\hline t-rESP & Response Time & Enter the time allowed for a slave device to respond to a command. & d.5P.dP & Display Decimal Point & Set the decimal point position for the display. This is independent from float decimal point. \\
\hline SLRUE & Slave & Enter Slave Mode & \multirow[t]{3}{*}{FLot.dP} & \multirow[t]{3}{*}{Floating Decimal Point} & \multirow[t]{3}{*}{Floating Decimal Point. Select the decimal point for the expected floating point data.} \\
\hline diter & Data Type & Enter the Data Type for each PV & & & \\
\hline \multirow[t]{3}{*}{FLont} & \multirow[t]{3}{*}{Floating Point Data Type} & \multirow[t]{3}{*}{Floating Point Data Type. Select Floating Point as the data type to be read from the slave device.} & & & \\
\hline & & & 5LRLE & Scale PV & Scale PV \\
\hline & & & inP & Input 1 & Program input 1 value \\
\hline \multirow[t]{2}{*}{Short} & \multirow[t]{2}{*}{Short Integer Data Type} & \multirow[t]{2}{*}{Short Integer Data Type. Select Short Integer as the data type to be read from the slave device.} & d.5 & Display 1 & Program display 1 value \\
\hline & & & inp 2 & Input 2 & Program input 2 value (up to 32 points for PV1 \& PV2) \\
\hline \multirow[t]{3}{*}{Lonis} & \multirow[t]{3}{*}{Long Integer Data Type} & \multirow[t]{3}{*}{Long Integer Data Type. Select Long Integer as the data type to be read from the slave device.} & d.5 2 & Display 2 & Program display 2 value (up to 32 points for PV1 \& PV2) \\
\hline & & & d5PLR4 & Display & Enter Display Setup menu \\
\hline & & & LinE i & Display Line 1 & Top Display \\
\hline \multirow[t]{2}{*}{ל} & \multirow[t]{2}{*}{Binary} & \multirow[t]{2}{*}{Binary Data. Select Binary format for Short or Long integers.} & d PU & Display PV & Display PVs 1-16 \\
\hline & & & \multirow[t]{2}{*}{d Eh-L} & \multirow[t]{2}{*}{Display C Channel} & \multirow[t]{2}{*}{Display Math Channels C1C4} \\
\hline \multirow[t]{2}{*}{bed} & \multirow[t]{2}{*}{\(B C D\)} & \multirow[t]{2}{*}{BCD Data. Select BCD format for Short or Long integers.} & & & \\
\hline & & & Pium it & Display PV \& Units & Display PV \& Units \\
\hline 5 LunEd & Signed & Signed Data. Select Signed Binary format for Short or Long integers. & tupun & Display Tag, PV Number & Display Tag \& PV Number selected \\
\hline \multirow[t]{2}{*}{un5 ind} & \multirow[t]{2}{*}{Unsigned} & \multirow[t]{2}{*}{Unsigned Data. Select Unsigned Binary format for Short or Long integers.} & tupinu & Display Tag, PV\# \& Units & Display Tag, PV Number selected, \& Units \\
\hline & & & C.un it & Display C \& Units & Display C1-C4 \& Units \\
\hline 1234 & Byte Order & Select big-endian byte order. & tE. E. u & Display Tag, C, \& Units & Display Tag, C1-C4 \& Units \\
\hline 4321 & Byte Order & Select little-endian byte order. & d5Et & Display Set Points 1-8 & Display Set Points 1-8 \\
\hline 2413 & Byte Order & Select byte-swapped bigendian byte order. Not available for Short integer. & H,-PU & \[
\begin{aligned}
& \text { Display Max PV } \\
& 1-16
\end{aligned}
\] & Display Maximum value for each enabled PV1-16 \\
\hline \multirow[t]{2}{*}{3412} & \multirow[t]{2}{*}{Byte Order} & \multirow[t]{2}{*}{Select byte-swapped littleendian byte order. Not available for Short integer.} & Lo-Pu & \[
\begin{aligned}
& \text { Display Min PV } \\
& 1-16
\end{aligned}
\] & Display Minimum value for each enabled PV1-16 \\
\hline & & & \(\mathrm{H}_{1}\) - & \[
\begin{aligned}
& \text { Display Max Ch } \\
& \text { C1-C4 }
\end{aligned}
\] & Display Maximum for math channels C1-C4 \\
\hline t-rESP & Response Time & Enter the time allowed for a slave device to respond to a command. & Lo-L & Display Min Ch C1-C4 & Display Minimum for math channels C1-C4 \\
\hline 5Etup & Setup & Enter Setup menu & LinE 2 & Display Line 2 & Bottom Display \\
\hline PU & \begin{tabular}{l}
Process \\
Variable
\end{tabular} & Enter PV Setup menu & d LRL & Display Tag & Display Tag \\
\hline PU & PV & Select PV 1-16 & d tRE.u & Display Tag \& Units & Display Tag \& Units \\
\hline
\end{tabular}

DPM-100 Modbus \({ }^{\circledR}\) Display Instruction Manual
\begin{tabular}{|c|c|c|c|c|c|}
\hline Display & Parameter & Description & Display & Parameter & Description \\
\hline d off & Display off & Display Off & \multirow[t]{3}{*}{OfF} & \multirow[t]{3}{*}{Off} & \multirow[t]{3}{*}{Relay goes to non-alarm condition when break detected. Relay turns off when Communications Break detected.} \\
\hline d-inty & Display Intensity & Display Intensity & & & \\
\hline rELRy & Relay Setup & Enter Relay Setup menu & & & \\
\hline 855 & Assign Relay & Assign Relay menu & Rout & Analog output & Enter the Analog Output scaling menu \\
\hline reLRy & Relay 1-8 & Assign Relay 1-8 & \multirow[t]{2}{*}{ROut 1*} & \multirow[b]{2}{*}{Aout channel} & \multirow[t]{2}{*}{Analog Output source channel (*1-3)} \\
\hline PU & PV 1-16 & Map Relay to PV 1-16 & & & \\
\hline ר-P & Multiple PVs & Map Relay to Multiple PVs & \multirow[t]{2}{*}{d.5 1} & \multirow[t]{2}{*}{Display 1} & \multirow[t]{2}{*}{Program the first Display value for the Analog Output.} \\
\hline riy i & Relay 1-8 & Relay 1-8 & & & \\
\hline Rat 1 & Relay Action 18 & Assign Relay Action for relays 1-8 & \multirow[t]{3}{*}{Sut} & \multirow[t]{3}{*}{Output 1} & \multirow[t]{3}{*}{Program the first Output value that corresponds to the Display 1 value for the Analog Output. (e.g. 4.000 mA ).} \\
\hline Ruto & Automatic & Set relay for automatic reset & & & \\
\hline R-mาR & Auto-manual & Set relay for auto or manual & & & \\
\hline & & reset any time & d 52 & Display 2 & Program the second Display value for the Analog Output. \\
\hline LRECH & Latching & Set relay for latching operation & \multirow[t]{2}{*}{Sut 2} & \multirow[t]{2}{*}{Output 2} & \multirow[t]{2}{*}{Program the second Output value that corresponds to the Display 2 value for the Analog Output. (e.g. 4.000 \(\mathrm{mA})\). (e.g. 20.000 mA )} \\
\hline Lt-ELr & Latchingcleared & Set relay for latching operation with manual reset only after alarm condition has cleared & & & \\
\hline RLtErn & Alternate & & SEr inil & Serial & Enter Serial menu \\
\hline & & alternation control & 5cRn id & Scan ID & Enter Scan ID of the meter being polled (1-247) \\
\hline 5Rn P PL & Sample & Set relay for sample time trigger control & \multirow[t]{4}{*}{brud} & \multirow[t]{4}{*}{Baud Rate} & \multirow[t]{2}{*}{Select Baud Rate (Choices: 300/600/1200/2400/4800/96 00/19,200)} \\
\hline BFF & Off & Turn relay off & & & \\
\hline FR iL5 & Fail-safe & Enter Fail-safe menu & & & \multirow[t]{2}{*}{(Must match that of other devices)} \\
\hline \multirow[t]{2}{*}{FL5} & \multirow[t]{2}{*}{Fail-safe 1} & \multirow[t]{2}{*}{Set relay 1-8 fail-safe operation} & & & \\
\hline & & & \multirow[t]{3}{*}{tr dity} & \multirow[t]{3}{*}{Transmit Delay} & \multirow[t]{3}{*}{Enter Transmit Delay (Master's delay must be greater than Snooper or slave devices)} \\
\hline on & On & Enable fail-safe operation & & & \\
\hline off & Off & Disable fail-safe operation & & & \\
\hline dELRy & Delay & Enter relay Time Delay menu & \multirow[t]{2}{*}{PRr ity} & \multirow[t]{2}{*}{Parity} & \multirow[t]{2}{*}{\begin{tabular}{l}
Select Parity (Even, Odd, None 1-Stop, or None 2Stop) \\
(Must match that of other devices)
\end{tabular}} \\
\hline dil t* & Delay 1* & *Enter relay 1-8 time delay setup & & & \\
\hline On i & On 1 & Set relay 1 On time delay & \multirow[t]{3}{*}{t-btt} & \multirow[t]{3}{*}{Byte-to-byte Timeout} & \multirow[t]{3}{*}{\begin{tabular}{l}
Enter the timeout value allowed between received bytes. \\
(This is used to fix communication problems with slow devices).
\end{tabular}} \\
\hline OFF 1 & Off 1 & Set relay 1 Off time delay & & & \\
\hline brERH & Break & Set relay condition if communication break detected & & & \\
\hline \multirow[t]{2}{*}{no Rict} & \multirow[t]{2}{*}{No action} & \multirow[t]{2}{*}{Ignore break condition. No change in relay state when Communications Break detected.} & P855 & Password & Enter the Password menu \\
\hline & & & P955 & Password 1 & Set or enter Password 1 \\
\hline \multirow[t]{5}{*}{0 O} & \multirow[t]{5}{*}{On} & \multirow[t]{5}{*}{Relay goes to alarm condition when break detected. Relay turns on when Communications Break detected.} & PR55 2 & Password 2 & Set or enter Password 2 \\
\hline & & & PR55 3 & Password 3 & Set or enter Password 3 \\
\hline & & & unioc & Unlocked & Program password to lock scanner \\
\hline & & & Locd & Locked & Enter password to unlock scanner \\
\hline & & & \[
\begin{aligned}
& \hline 999999 \\
& -99999
\end{aligned}
\] & Flashing & Over/under range condition \\
\hline
\end{tabular}

\section*{ScanView Software}

The meter can also be programmed using the PC-based ScanView software included with the meter. This software is can be installed on any Microsoft® Windows \({ }^{®}\) (XP/Vista/7/8/10) computer by connecting to the meter's onboard USB. The meter is powered by the USB connection, so there is no need to wire anything prior to programming the meter, though USB is intended only for meter configuration.

\section*{ScanView Installation}
1. Connect one end of the provided USB cable to the meter and the other end to the computer. The computer will automatically install the driver software it needs to talk to the meter. Only one meter may be connected at a time. Attaching multiple meters will cause a conflict with the meter software.

2. Once the driver is installed, an AutoPlay dialog should appear for the drive "MSINSTAL." Click "Open folder to view files." If the computer does not display an AutoPlay dialog for the drive "MSINSTAL," you should open My Computer and doubleclick on the drive labeled "MSINSTAL."
3. Double-click on the file named "MSStart." The program will open a few windows and install two programs on your computer. Simply follow the onscreen instructions until you see one of the dialogs below. If you receive a "User Account Control" warning, click "Yes."
4. If there is an update available, click the "Update" button to install the new version. Otherwise, click "Configure" to begin
 programming your meter.
\begin{tabular}{|c|c|}
\hline \multicolumn{2}{|l|}{ScanView} \\
\hline \multicolumn{2}{|l|}{Exit USB Connection About} \\
\hline \multicolumn{2}{|l|}{Confirm} \\
\hline \multicolumn{2}{|l|}{Update ScanView with version 3_9_3from online repository?} \\
\hline Update & Cancel \\
\hline \multicolumn{2}{|l|}{Status} \\
\hline
\end{tabular}


Note: If you decide to update your ScanView installation, once the installation has completed, you will be asked if you want to update the installation files located on the meter itself. This way, you will always have the most current installation version on the meter for future installs.
Warning! \begin{tabular}{l|l} 
- Do not unplug the meter while the new installation files are being written to it. The \\
meter will display uar tE during the process and you will receive an onscreen \\
notification once the process is complete. \\
- Do not disconnect and reconnect the meter rapidly. Allow at least 10 seconds from \\
disconnection before reconnecting USB to the meter.
\end{tabular}

Monitoring and data logging for one scanner (Master mode) is available with ScanView software. All the enabled PVs and math channels may be logged to a single .csv file. The ScanView software synchronizes with the scanner in master mode one second after the scanner has completed a polling cycle.
Note: The poll time of the scanner must be greater than 5 seconds to prevent collisions on the bus.

\section*{Menu Navigation Tip}
- The Up arrow scrolls through the sub-menus within a menu, after the last item it returns to the top menu. Press Enter to step into the menu again or press Up arrow to move to the next menu. Note: There are some exceptions (e.g. PV - Enable - - Data type \(\mathbf{\Delta}\) Next PV).
- Press Menu to exit programming at any time.


\section*{Setting Numeric Values}

The numeric values are set using the Right and Up arrow buttons. Press the Right arrow to select the next digit and the Up arrow to increment the digit's value. The digit being changed is displayed brighter than the rest. Press and hold the Up arrow to auto-increment the display value. Press the Enter button, at any time, to accept a setting or the Menu button to exit without saving changes.


\section*{Main Menu}

The main menu consists of the most commonly used functions: Mode, Setup, Serial, and Password.
- Press Menu button to enter Scanner Programming
- Press Up arrow button to scroll through the menus
- Press Menu, at any time, to exit and return to Run Mode
- Changes to the settings are saved to memory only after pressing Enter
- The display moves to the next menu every time a setting is accepted by pressing Enter


\section*{DPM-100 Modbus \({ }^{\circledR}\) Display Instruction Manual}

\section*{Serial Communications (5Er , RL)}

The scanner is equipped with RS-485 Modbus RTU serial communications.
The Serial menu is used for programming the Scanner ID, Baud Rate, Transmit Delay, Parity, and Byte-toByte Timeout parameters.
The meter may be connected to a PC for initial configuration via the onboard micro USB connection. For ongoing digital communications with a computer or other data terminal equipment, an RS-232, or RS-485 option is required; see Ordering Information on page 6 for details.

Do not connect any equipment other than BinMaster's expansion modules, cables, or scanners to the RJ45 M-LINK connector. Otherwise damage will occur to the equipment and the scanner.

When using more than one scanner in a multi-drop mode, each scanner must be provided with its own unique address. The scanner address (Scan ID) may be programmed between 1 and 247 .
The transmit delay may be set between 0 and 4999 ms ; this value must be less than (Poll Time/\# of PVs).
The parity can be set to even, odd, or none with 1 or 2 stop bits.
Changes made to the Serial menu are initialized after exiting the Serial menu.


When setting up the scanner to run on a Modbus system, the devices must be programmed with matching Baud Rate and Parity. Failure to match up the network devices' parameters may result in communication breaks.
Notes:
1. The byte-to-byte timeout setting may be adjusted to fix communication errors with slow devices.
2. The Transmit Delay of the Master must be greater than the Snooper or the slave devices being polled.
3. When using the M-Link to connect to a Modbus network, the DPM-100 cannot be used as a Master, but can be used as a Snooper or as a Slave. In order to use the DPM-100 as a Master, the scanner must connect to the Modbus Network via the three-wire terminal connector on the back of the scanner.

\section*{Scanner Mode Selection}

\section*{Operating Modes (modE)}

The Mode menu is used to select how the scanner is to function:
1. Master: Reads a slave device, scales the data from it, displays the result, and operates the relays and \(4-20 \mathrm{~mA}\) output. The Master polls from 1 to 16 process variables from 1 to 16 slave devices. The Master processes and displays PV1 through PV16 and alternately displays the variables being polled.
2. Snooper: Listens to the Modbus traffic and picks up a specific register or registers being polled by a Master device from a specific slave device and processes the data being read.
3. Slave: Read and controlled by a master device (PLC, DCS, etc). The data sent to it by the master is scaled, displayed, and used to operate the relays and 4-20 mA output.

The Master mode requires additional parameter selection to specify how the slave device is to be read and how to interpret the data.
Press Menu to enter Scanner Programming. Press the Enter button to access any menu or press Up arrow button to scroll through choices. Press the Menu button to exit at any time and return to Run mode.


\section*{How to Enable Process Variables (PVs)}

In Master or Snooper Mode, navigate to the PV Number menu and press ENTER. From there, the user can scroll through all of the sixteen available PVs. In order to enable a specific PV, simply press ENTER to access the desired PV, then scroll to ENABLE and press ENTER (Follow the same course of action for disabling PVs).
Enter the Slave ID of the device being polled by the Master, followed by the Function Code, Register Number, Data Type, and Byte Order.
Once the desired PVs are enabled, navigate to the Setup menu and enter the PV Setup in order to select the PV tag, units, format, and decimal point parameters, as well as to scale the PVs.

Once the user has scaled the final PV, the scanner automatically goes to the Display Setup menu to access line 1 and 2 display assignments.
By default, display line 1 is assigned to Display PV (d PU) and line 2 to display the Tag (d tRE) for the corresponding PV.
It is possible to display PVs \& Tags on line 1 and 2 simultaneously by selecting Tag \& PV Number (tREPUn). Display line 1 is setup by default to display PV \& tag for PV1, 3, 5,7 ; while line 2 is setup by default to display PV \& tag 2, 4, 6, 8. These can be changed by the user to display any or all PVs. Program either display line 1 or 2 to show the desired parameters and press ENTER. See page 32 for details.

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\section*{Master Mode (nרRStr)}

The Master mode contains the PV Number, Poll Time, and Response Timeout menus.
PV Number: Enable/disable PVs, select slave ID, function code, register number, data type \& byte order.
Poll Time: Enter the time interval to poll the slave devices selected.
Response timeout: Enter the time interval to wait after three polls before reporting it as a Communications Break.


\section*{Snooper Mode (5nooPr)}

The Snooper mode is used to listen to data being transmitted on the bus. Multiple Snoopers can be connected to the RS-485 bus and display any process variable. The same process variable can be displayed in multiple locations. Use the menu below to configure Snooper Mode parameters.


Notes:
1. To minimize the possibility of communication errors and communication break conditions, use a poll time of 5 seconds or more with slow baud rates (e.g. 4800 bps or less).
2. The response time for scanners set up for Snooper mode must be greater than the Master's poll time. This setting corresponds to the time window during which the Snooper listens to the bus for a reply by the slave device being polled by the master device. As soon as the Snooper detects a new reply on the bus, the display is updated. If there is no reply within the response time setting, the Snooper goes into communications break condition.

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\section*{How to Select 5 or 6-Digit Registers}

In Master or Snooper Mode, it is possible to select either a five-digit or a six-digit Register Number. Once the operator has enabled a PV, entered a Slave ID, and chosen a Function Code, the scanner will arrive at the Register Number menu (rEunbr). Press the Right arrow to display and then the Up arrow to change the setting for the number of digits used for the Register Number (5 div or \(\overline{6} \mathbf{d} \boldsymbol{d})\), then press ENTER.
Notes:
1. If Function Code 03 is selected, the Register Number defaults to 40001; if Function Code 04 is selected, the Register Number defaults to 30001.
2. Default Data Type is Float
3. Default Slave ID for PV1 \(=001\), for \(P V 2=002\), for \(P V 3=003\), etc.


The Master ignores the decimal point setting for slave devices that specify a Short or Long integer. For example, a slave that is displaying 12.34 is read as 1,234 . Floating point data may or may not utilize the decimal point. Refer to the slave's operating manual to make sure.
The Register Number range is based on the Function Code and the number of digits selected. See the following table:
\begin{tabular}{|c|c|c|}
\hline Function Code & 5 Digit & 6 Digit \\
\hline 03 & \(40001-49999\) & \(400001-465536\) \\
\hline 04 & \(30001-39999\) & \(300001-365536\) \\
\hline 65 & \(65001-65999\) & \(\mathrm{~N} / \mathrm{A}\) \\
\hline
\end{tabular}

\section*{Slave Mode (5LRUE)}

The Slave mode is capable of accepting Short, Long, and Float data types. Refer to the Modbus Register Tables at www.binmaster.com for details of all the predefined parameters. Follow the menu below to navigate and set all parameters for Slave Mode.


\section*{Setting Up the Scanner (5EEuP)}

The Setup menu is used to select:
1. PV Setup
a. PV Tags
b. PV Units
c. Format: Decimal point or Feet \& Inches
d. Decimal Point
e. Scale input data
2. Display assignment \& Intensity
3. Relay assignment and operation
4. \(4-20 \mathrm{~mA}\) analog output scaling

Press the Menu button to exit at any time.


\section*{Setting Up the Process Variables (PVs) (PU 5EtuP)}

Enter the \(P V\) Setup menu to set up all the criteria associated with each enabled PV. Once you have selected the desired PV, you can select parameters for each. These include tag, units, format, display decimal point, float decimal point (resolution), and scaling of the input data.
Note: PV1 and PV2 can have multiple points for linearization. Only two points are available for all other PVs and for either the Square Root or Programmable Exponent functions.


\section*{Setting the Display Decimal Point (d sP.dP)}

Decimal point may be set one to five decimal places or with no decimal point at all. Pressing the Up arrow moves the decimal point one place to the right until no decimal point is displayed, and then it moves to the leftmost position. The decimal point is programmable only for the Display Value.

\section*{Setting the Float Decimal Point (FLot.dP)}

If floating point data type is selected, select the number of decimals to correspond to the expected floating-point data; the numbers to right of the LSD will be ignored by the scanner.

\section*{Example:}

If you have a number such as 12.3456, you have to tell the scanner how many digits to the right are of interest to you. In this case selecting 4 places will make use of all the digits. For most applications the display decimal point will be set accordingly (i.e. 4 places).
If 2 decimal places are selected, the number 12.3456 is displayed as 12.35 ; notice that the number is rounded up.

\section*{Scaling the PV Display Values (5LRLE)}

The data that the scanner receives can be scaled to display in engineering units. Input 1 must be less than Input 2; Input 2 must be less than Input 3; etc. (known as monotonic values). Press Enter to save the changes or Menu to exit without saving. When the Linear function is selected for PV1 \& PV2, up to 32 points may be programmed to handle non-linear data. Only two points are available for all other PVs and for either the Square Root or Programmable Exponent functions. Round Horizontal Tanks are scaled using the length and diameter of the tank.

\section*{Scale Menu}


The display will show Error if the scaling process is unsuccessful. Undesired operation may occur if the error is not corrected. Correct the error by either changing one of the inputs in question or changing the number of points to exclude an erroneous input point.
Note: Scaling Short and Long input values (input 1, input 2, etc.) should be done without the decimal point.

\section*{Multi-Point Linearization (L mERr)}

The scanner is set up at the factory for 2-point linear scaling. Up to 32 linearization points may be selected for PV1 and PV2. All other PVs have two linearization points available. See page 56 for details.

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\section*{Setting Up the Displays (d5PLRY 5ELuP)}

Line 1 Parameters (LinE 1 d5PLRy)
The top display ( \(\mathbf{L}, \cap E \quad\) I) can be programmed to display any of the following:
\begin{tabular}{|c|c|c|}
\hline Display & Parameter & Setting Description \\
\hline d Pu & Display PV & Display PVs 1-16 \\
\hline d [h-L & Display C Channel & Display Math Channels C1-C4 \\
\hline Puiun it & Display PV \& Units & Display PV \& Units \\
\hline tuplin & Display Tag, PV Number & Display Tag \& PV Number selected \\
\hline tupuinu & Display Tag, PV\# \& Units & Display Tag, PV Number selected, \& Units \\
\hline E.un it & Display C \& Units & Display C1-C4 \& Units \\
\hline t¢. ᄃ. u & Display Tag, C, \& Units & Display Tag, C1-C4 \& Units \\
\hline dSEt \({ }^{\text {f }}\) & Display Set Points 1-8 & Display Set Points 1-8 \\
\hline \(\mathrm{H}_{1}-\mathrm{PU}\) & Display Max PV 1-16 & Display Maximum value for each enabled PV1-16 \\
\hline Lo-Pu & Display Min PV 1-16 & Display Minimum value for each enabled PV1-16 \\
\hline H,-L & Display Max Ch C1-C4 & Display Maximum for math channels C1-C4 \\
\hline Lo-L & Display Min Ch C1-C4 & Display Minimum for math channels C1-C4 \\
\hline
\end{tabular}

\section*{Line 2 Parameters (LinE 2 d5PLRy)}

The bottom display ( \(\mathbf{L}, \mathrm{nE} \boldsymbol{Z}\) ) can be programmed to display any of the following:
\begin{tabular}{|c|c|c|}
\hline Display & Parameter & Setting Description \\
\hline d PU & Display PV & Display PVs 1-16 \\
\hline d Ch-L & Display C Channel & Display Math Channels C1-C4 \\
\hline Puiun it & Display PV \& Units & Display PV \& Units \\
\hline tupuin & Display Tag, PV Number & Display Tag \& PV Number selected \\
\hline tL.PUnu & Display Tag, PV\# \& Units & Display Tag, PV Number selected, \& Units \\
\hline C.un it & Display C \& Units & Display C1-C4 \& Units \\
\hline tL. C. u & Display Tag, C, \& Units & Display Tag, C1-C4 \& Units \\
\hline d5Et i & Display Set Points 1-8 & Display Set Points 1-8 \\
\hline H,-PU & Display Max PV 1-16 & Display Maximum value for each enabled PV1-16 \\
\hline Lo-PU & Display Min PV 1-16 & Display Minimum value for each enabled PV1-16 \\
\hline H,-L & Display Max Ch C1-C4 & Display Maximum for math channels C1-C4 \\
\hline Lo-L & Display Min Ch C1-C4 & Display Minimum for math channels C1-C4 \\
\hline d LRE & Display Tag & Display Tag (Line 2 only) \\
\hline d EREu & Display Tag \& Units & Display Tag \& Units (Line 2 only) \\
\hline d off & Display off & Display Off (Line 2 only) \\
\hline
\end{tabular}

Note: Toggling displays use the Scan Time for the value and 2 seconds for Tag and Units.

\section*{Display Intensity (d-inty)}

The scanner has eight display intensity levels to give the best performance under various lighting conditions. Select intensity 8 for outdoor applications. The default intensity setting is 8 .

Display Line 1 Menu ( \(L\) inE 1 d5PLRY)


Note: For Tag-PVn and Tag-PVn-U, the default settings for PVs are 1,3,5,\&7, followed by two underscores, which represent empty PVs. These all can be changed to any enabled PVs.

Display Line 2 Menu ( \(L \operatorname{me} 2\) dSPLRY)


Note: For Tag-PVn and Tag-PVn-U, the default settings for PVs are 2,4,6,\& 8, followed by two underscores, which represent empty PVs. These all can be changed to any enabled PVs.

\section*{Setting the Tags（LRE）\＆Units（un th5）}

Each PV can be setup with its own tag and units．See the flow charts on the previous pages to access the display menu to show the tag or toggling tag \＆units．The engineering units and custom tags can be set using the following 7 －segment character set：
\begin{tabular}{|c|c|}
\hline Display & Character \\
\hline \(\mathbf{D}\) & 0 \\
\hline \(\mathbf{i}\) & 1 \\
\hline \(\mathbf{Z}\) & 2 \\
\hline 3 & 3 \\
\hline \(\mathbf{4}\) & 4 \\
\hline 5 & 5 \\
\hline \(\mathbf{5}\) & 6 \\
\hline \(\mathbf{7}\) & 7 \\
\hline \(\mathbf{8}\) & 8 \\
\hline \(\mathbf{9}\) & 9 \\
\hline \(\mathbf{R}\) & A \\
\hline \(\mathbf{b}\) & b \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Display & Character \\
\hline ［ & C \\
\hline C & c \\
\hline d & d \\
\hline E & E \\
\hline \(F\) & F \\
\hline \(\square\) & G \\
\hline 9 & g \\
\hline H & H \\
\hline h & h \\
\hline 1 & 1 \\
\hline 1 & i \\
\hline 」 & \(J\) \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Display & Character \\
\hline \(\boldsymbol{H}\) & K \\
\hline \(\mathbf{L}\) & L \\
\hline \(\boldsymbol{n} \mathbf{~ T}\) & m \\
\hline \(\boldsymbol{n}\) & n \\
\hline \(\mathbf{D}\) & 0 \\
\hline \(\mathbf{a}\) & 0 \\
\hline \(\mathbf{P}\) & P \\
\hline \(\mathbf{7}\) & q \\
\hline \(\mathbf{r}\) & r \\
\hline \(\mathbf{5}\) & S \\
\hline \(\mathbf{L}\) & t \\
\hline \(\mathbf{u}\) & u \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Display & Character \\
\hline 1 & V \\
\hline 山」 & w \\
\hline H & X \\
\hline צ & Y \\
\hline 2 & Z \\
\hline － & － \\
\hline － & 1 \\
\hline ［ & ］ \\
\hline J & ［ \\
\hline ＝ & ＝ \\
\hline 0 & Degree（＜） \\
\hline & Space \\
\hline
\end{tabular}

Notes：Degree symbol represented by（＜）if programming with ScanView．The letters＂m＂and＂w＂use two 7 －segment LEDs each；when selected the characters to the right are shifted one position．Press and hold up arrow to auto－scroll the characters in the display．

\section*{Application Example 1}

In this application，we have a system consisting of（4）BinMaster NCR－80 multivariable tank level gauges connected to a DPM－100 displaying feet of product．


Register Numbers \＆Process Variables
32003 －Feet of Product
32005 －Distance to Product（ft）
32007 －Linear Percent

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The following table shows the system setup for the BinMaster NCR-80, one DPM-100 Master, and one DPM-100 Snooper:
\begin{tabular}{|c|c|c|c|}
\hline Parameter & DPM-100 & DPM-100 & Description/Comment \\
\hline Mode & Master & Snooper & \\
\hline PV1 Slave ID & 1 & 1 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV1 & 32003 & 32003 & Tank 1 Product Level in Feet \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV2 Slave ID & 1 & 1 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV2 & 32005 & 32005 & Tank 1 Distance to Product (ft) \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV3 Slave ID & 1 & 1 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV3 & 32007 & 32007 & Tank 1 Linear Percent \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV4 Slave ID & 2 & 2 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV4 & 32003 & 32003 & Tank 2 Product Level in Feet \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV5 Slave ID & 2 & 2 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV5 & 32005 & 32005 & Tank 2 Distance to Product (ft) \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV6 Slave ID & 2 & 2 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV6 & 32007 & 32007 & Tank 2 Linear Percent \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV7 Slave ID & 3 & 3 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV7 & 32003 & 32003 & Tank 3 Product Level in Feet \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline
\end{tabular}

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\begin{tabular}{|c|c|c|c|}
\hline Parameter & DPM-100 & DPM-100 & Description/Comment \\
\hline PV8 Slave ID & 3 & 3 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV8 & 32005 & 32005 & Tank 3 Distance to Product (ft) \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV9 Slave ID & 3 & 3 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV9 & 32007 & 32007 & Tank 3 Linear Percent \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV10 Slave ID & 4 & 4 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV10 & 32003 & 32003 & Tank 4 Product Level in Feet \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV11 Slave ID & 4 & 4 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV11 & 32005 & 32005 & Tank 4 Distance to Product (ft) \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline PV12 Slave ID & 4 & 4 & \\
\hline Function Code & 04 & 04 & \\
\hline Register PV12 & 32007 & 32007 & Tank 4 Linear Percent \\
\hline Data Type & Float & Float & \\
\hline Byte Order & 1234 & 1234 & \\
\hline Scanner ID & 246 & 245 & \\
\hline Polling Time & 5.0 sec & N/A & \\
\hline Slave Response Timeout & 10.0 sec & 10.0 sec & \\
\hline Baud & 9600 & 9600 & \\
\hline Parity & None 1 & None 1 & 1 stop bit \\
\hline Byte-to-Byte Timeout & 0.01 sec & 0.01 sec & \\
\hline Decimal point & 3 places & 3 places & \\
\hline Input 1 & 000000 & 000000 & Scaling for Level \& Interface \\
\hline Display 1 & 000000 & 000000 & \\
\hline Input 2 & 999999 & 999999 & 0.001 inch resolution \\
\hline Display 2 & 83.333 & 83.333 & Feet \\
\hline
\end{tabular}

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\section*{Application Example 2}

In this application, we have a system consisting of (4) BinMaster NCR-80 multivariable tank level gauges connected to a DPM-100 displaying feet of product, distance to product in feet, and linear percent. The display readout is shown in linear percent.


\section*{Register Numbers \& Process Variables}

32003 - Feet of Product
32005 - Distance to Product (ft)
32007 - Linear Percent

\section*{Setting the Relay Operation (rELRY)}

This menu is used to set up the assignment and operation of the relays.
Relay Setup Menu (rELRy SEtuP)


During setup, the relays do not follow the input and they will remain in the state found prior to entering the Relay menu.
1. R55 Ren Relay assignment
a. Assign relay to PV
b. Assign relay to Math channel
c. Assign relay to multiple PVs (2 to 16 PVs )
2. Rct I Relay action
a. Automatic reset only (non-latching)
b. Automatic + manual reset at any time (non-latching)
c. Latching (manual reset only)
d. Latching with Clear (manual reset only after alarm condition has cleared)
e. Pump alternation control (automatic reset only)
f. Sampling (the relay is activated for a user-specified time)
g. Off (relay state controlled by Interlock feature)
3. 5Et I Set point \& r 5t 1 Reset point
4. FR ILSF Fail-safe operation
a. On (enabled)
b. Off (disabled)
5. dELRY Time delay
a. On delay (0-999.9 seconds)
b. Off delay (0-999.9 seconds)
6. brERH Relay action for communications break

\section*{Setting the Relay Action (Rat}

Operation of the relays is programmed in the Action menu. The relays may be set up for any of the following modes of operation:
1. Ruto Automatic reset (non-latching)
2. \(R-n\) - \(\mathrm{Rn}_{n}\) Automatic + manual reset at any time (non-latching)
3. LREcH Latching (manual reset only, at any time)
4. Lt-[Lr Latching with Clear (manual reset only after alarm condition has cleared)
5. Rltern Pump alternation control (automatic reset only)
6. 5RnרPL Sampling (the relay is activated for a user-specified time)
7. ofF Off (relay state controlled by Interlock feature)

The following graphic shows relay 1 action setup; relay 2-8 are set up in a similar fashion.


\section*{Programming Set (5Et) \& Reset (r5t) Points}

High alarm indication: program set point above reset point.
Low alarm indication: program set point below reset point.
The deadband is defined as the difference between set and reset points. Minimum deadband is one display count. If the set and reset points are programmed with the same value, the relay will reset one count below the set point.
Note: Changes are not saved until the reset point has been accepted.


\section*{Setting Fail-Safe Operation (FR iL5F)}

In fail-safe mode of operation, the relay coil is energized when the process variable is within safe limits and the relay coil is de-energized when the alarm condition exists. The fail-safe operation is set independently for each relay. Select on to enable or select oFF to disable fail-safe operation.

\section*{Programming Time Delay (dELRY)}

The On and Off time delays may be programmed for each relay between 0 and 999.9 seconds. The relays will transfer only after the condition has been maintained for the corresponding time delay.
The On time delay is associated with the set point.
The Off time delay is associated with the reset point.

\section*{Relay Action for Communications Break (brERH)}

The Scanner will poll the slave device three times before reporting a communications break condition. After the third failure, the Response Timeout timer starts and will determine the actual time to report a PV in break condition.
1. Turn On (Go to alarm condition)
2. Turn Off (Go to non-alarm condition)
3. No Action (The relays will maintain the last condition)

\section*{Relay and Alarm Operation Diagrams}

The following graphs illustrate the operation of the relays, status LEDs, and ACK button.


For Manual reset mode, ACK can be pressed anytime to turn "off" relay. To detect a new alarm condition, the signal must go below the set point, and then go above it.

Low Alarm Operation (Set < Reset)


For Manual reset mode, ACK can be pressed anytime to turn "off" relay. For relay to turn back "on", signal must go above set point, and then go below it.

High Alarm with Fail-Safe Operation (Set > Reset)


Note: Relay coil is energized in non-alarm condition. In case of power failure, relay will go to alarm state.

Low Alarm with Fail-Safe Operation (Set < Reset)


\section*{Pump Alternation Control Operation}


\section*{Relay Sampling Operation}


When the signal crosses the set point, the relay trips and the sample time starts. After the sample time has elapsed, the relay resets. The cycle repeats every time the set point is crossed, going up for high alarms and going down for low alarms.
The sample time can be programmed between 0.1 and 5999.9 seconds.

\section*{Relay Operation After Communications Break}

When a Master scanner fails to receive a reply from the slave it is called a Communications Break. The relays can be programmed to react to this event by going On, Off, or No Action. After communication is restored the relays are turned off or on, based on their operating mode and their set and reset points, without regard to their prior state. This is similar to the auto initialization on power up. Below is a diagram showing three examples.
The same is true for a scanner set up to operate in Snooper mode.


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\section*{Time Delay Operation}

The following graphs show the operation of the time delay function.


\section*{Off Time Delay}

When the signal crosses the set point, the On time delay timer starts and the relay trips when the time delay has elapsed. If the signal drops below the set point (high alarm) before the time delay has elapsed, the On time delay timer resets and the relay does not change state. The same principle applies to the Off time delay.
Note: If "Automatic or Manual ( \(\boldsymbol{\beta}-\mathrm{n}\) า Rn )" reset mode is selected, the LED follows the reset point and not the relay state when the relay is acknowledged.

\section*{Relay Operation Details}

\section*{Overview}

The relay capabilities of the scanner expand its usefulness beyond simple indication to provide users with alarm and control functions. These capabilities include front panel alarm status LEDs, as well as either 2 or 4 optional internal relays, and/or 4 external relays via expansion modules. Typical applications include high or low temperature, level, pressure or flow alarms, control applications such as simple on/off pump control, and pump alternation control for up to 8 pumps. There are four basic ways the relays can be used:
1. High or Low Alarms with Latching or Non-Latching Relays
2. Simple On/Off Control with \(100 \%\) Adjustable Deadband
3. Sampling (Based on Time)
4. Pump Alternation Control for up to 8 Pumps

\section*{Relays Auto Initialization}

When power is applied to the scanner, the front panel LEDs and alarm relays will reflect the state of the input to the scanner after the first response from the slave device. The following table indicates how the alarm LEDs and relays will react on power-up based on
\begin{tabular}{|c|c|c|c|c|c|}
\hline Alarm \# & \begin{tabular}{c} 
HI or LO \\
Alarm
\end{tabular} & \begin{tabular}{c} 
Set \\
Point
\end{tabular} & \begin{tabular}{c} 
Reset \\
Point
\end{tabular} & \begin{tabular}{c} 
Power-Up \\
Reading
\end{tabular} & \begin{tabular}{c} 
Relay \\
\& LED
\end{tabular} \\
\hline 1 & HI & 1000 & 500 & 499 & Off \\
\hline 2 & LO & 700 & 900 & 499 & On \\
\hline 3 & LO & 250 & 400 & 499 & Off \\
\hline 4 & HI & 450 & 200 & 499 & On \\
\hline
\end{tabular} the set and reset points:

\section*{Fail-Safe Operation (FR LL5F)}

The following table indicates how the relays behave based on the fail-safe selection for each relay:
\begin{tabular}{|l|l|l|l|l|l|}
\hline \begin{tabular}{l} 
Fail-Safe \\
Selection
\end{tabular} & \multicolumn{2}{|l|}{ Non-Alarm State } & \multicolumn{2}{|l|}{ Alarm State } & \multirow{2}{*}{ Power Failure } \\
\cline { 2 - 5 } & NO & NC & NO & NC & \\
\hline Off & Open & Closed & Closed & Open & \begin{tabular}{l} 
Relays go to \\
non-alarm state
\end{tabular} \\
\hline On & Closed & Open & Open & Closed & \begin{tabular}{l} 
Relays go to \\
alarm state
\end{tabular} \\
\hline
\end{tabular}

Note: \(N O=\) Normally Open, \(N C=\) Normally Closed. This refers to the condition of the relay contacts when the power to the scanner is off.

\section*{Front Panel LEDs}

The LEDs on the front panel provide status indication for the following:

The scanner is supplied with four alarm points that include front panel LEDs to indicate alarm conditions. This standard feature is particularly useful for alarm applications that require visual-only
\begin{tabular}{|c|c|c|c|}
\hline LED & Status & LED & Status \\
\hline 1 & Alarm 1 & 5 & Alarm 5 \\
\hline 2 & Alarm 2 & 6 & Alarm 6 \\
\hline 3 & Alarm 3 & 7 & Alarm 7 \\
\hline 4 & Alarm 4 & 8 & Alarm 8 \\
\hline
\end{tabular} indication. The LEDs are controlled by the set and reset points programmed by the user. When the display reaches a set point for a high or low alarm, the corresponding alarm LED will turn on. When the display returns to the reset point the LED will go off. The front panel LEDs respond differently for latching and nonlatching relays.
For non-latching relays, the LED is always off during normal condition and always on during alarm condition, regardless of the state of the relay (e.g. Relay acknowledged after alarm condition).
For latching relays, the alarm LEDs reflect the status of the relays, regardless of the alarm condition. The following tables illustrate how the alarm LEDs function in relation to the relays and the acknowledge button (Default: F3 key assigned to ACK):

Latching and Non-Latching Relay Operation
The relays can be set up for latching (manual reset) or non-latching (automatic reset) operation.

The On and Off terminology does not refer to the status of the relay's coil, which depends on the fail-safe mode selected.
\begin{tabular}{|c|l|}
\hline \multicolumn{2}{|c|}{ Relay terminology for following tables } \\
\hline Terminology & Relay Condition \\
\hline On & Alarm (Tripped) \\
\hline Off & Normal (Reset) \\
\hline Ack & Acknowledged \\
\hline
\end{tabular}
Warning! \begin{tabular}{l} 
In latching relay mode, latched \\
relays will reset (unlatch) \\
when power is cycled.
\end{tabular}

\section*{Non-Latching Relay (Ruto)}

In this application, the scanner is set up for automatic reset (non-latching relay). Acknowledging the alarm while it is still present has no effect on either the LED or the relay. When the alarm finally goes away, the relay automatically resets and the LED also goes off.
\begin{tabular}{|l|l|l|}
\hline \multicolumn{3}{|c|}{ Automatic reset only } \\
\hline Condition & LED & Relay \\
\hline Normal & Off & Off \\
\hline Alarm & On & On \\
\hline Ack (No effect) & On & On \\
\hline Normal & Off & Off \\
\hline
\end{tabular}

\section*{Non-Latching Relay (R-ח \(\boldsymbol{R}\) ( \(\boldsymbol{R}\) )}

In this application, the scanner is set up for automatic and manual reset at any time (non-latching relay). The LED and the relay automatically reset when the scanner returns to the normal condition.
The next time an alarm occurs, the operator acknowledges the alarm manually while the alarm condition still exists. This causes the relay to reset, but the LED stays on until the scanner returns to the normal condition.
\begin{tabular}{|l|l|l|}
\hline \multicolumn{3}{|c|}{ Automatic + manual reset any time } \\
\hline Condition & LED & Relay \\
\hline Normal & Off & Off \\
\hline Alarm & On & On \\
\hline Normal & Off & Off \\
\hline Next Alarm & On & On \\
\hline Ack & On & Off \\
\hline Normal & Off & Off \\
\hline
\end{tabular}

\section*{Latching Relay (LRtch)}

In this application, the scanner is set up for manual reset at any time. Acknowledging the alarm even if the alarm condition is still present resets the relay and turns off the LED.

\section*{Latching Relay (Lt-[Lr)}

In this application, the scanner is set up for manual reset only after the signal passes the reset point (alarm condition has cleared). Acknowledging the alarm while it is still present has no effect on either the LED or the relay. When the alarm is acknowledged after it returns to the normal state, the LED and the relay go off. Notice that the LED remains on, even after the scanner returns to the normal condition. This is because, for latching relays, the alarm LED reflects the status of the relay, regardless of the alarm condition.

\begin{tabular}{|l|l|l|}
\hline \multicolumn{3}{|c|}{\begin{tabular}{c} 
Manual reset only after alarm \\
condition has cleared
\end{tabular}} \\
\hline Condition & LED & Relay \\
\hline Normal & Off & Off \\
\hline Alarm & On & On \\
\hline Ack (No effect) & On & On \\
\hline Normal & On & On \\
\hline Ack & Off & Off \\
\hline
\end{tabular}

\section*{Acknowledging Relays}

There are two ways to acknowledge relays programmed for manual reset:
1. Via the programmable F4 digital input assigned to ACK (Default) and connected to a normally open pushbutton wired across F4 and COM.
2. Remotely via a normally open pushbutton wired across one of the digital inputs and the +5 V terminals on the digital I/O modules, which is triggered with a contact closure to COM, or with an active low signal (see page8).

When the ACK button or the assigned digital input is closed, all relays programmed for manual reset are acknowledged.


Figure 14. Acknowledge Relays with F4 Function Key


Figure 15. Acknowledge Relays with Digital Input

\section*{Pump Alternation Control Applications (RLLErn)}

For pump control applications where two or more similar pumps are used to control the level of a tank or a well, it is desirable to have all the pumps operate alternately. This prevents excessive wear and overheating of one pump over the lack of use of the other pumps.
Up to 8 relays can be set up to alternate every time an on/off pump cycle is completed. The set points and reset points can be programmed, so that the first pump on is the first pump off.

\section*{Application \#1: Pump Alternation Using Relays 1 \& 2}
1. Relays 1 and 2 are set up for pump alternation.
2. Relays 3 and 4 are set up for low and high alarm indication.
\begin{tabular}{|c|c|c|l|}
\hline \multicolumn{4}{|c|}{ Set and Reset Point Programming with Pump Alternation } \\
\hline Relay & Set Point & Reset Point & Function \\
\hline 1 & 30.000 & 10.000 & Controls pump 1 \& 2 \\
\hline 2 & 35.000 & 5.000 & Sets dual pump trigger \\
\hline 3 & 4.000 & 9.000 & Controls low alarm \\
\hline 4 & 40.000 & 29.000 & Controls high alarm \\
\hline
\end{tabular}

Pump Alternation Operation
1. Pump \#1 turns on when the level reaches 30.000 , when the level drops below 10.000 pump \#1 turns off.
2. The next time the level reaches 30.000 , pump \#2 turns on, when the level drops below 10.000 , pump \#2 turns off.
3. If the level doesn't reach 35.000 pump \#1 and pump \#2 will be operating alternately.
4. If pump \#1 cannot keep the level below 35.000 pump \#2 will turn on at 35.000 , then as the level drops to 10.000 pump \#1 turns off, pump \#2 is still running and shuts off below 5.000.
5. Notice that with the set and reset points of pump \#2 outside the range of pump \#1, the first pump on is the first pump to go off. This is true for up to 8 alternating pumps, if set up accordingly.
6. Relay \#3 will go into alarm if the level drops below 4.000 and relay \#4 will go into alarm if the level exceeds 40.000 .
7. Adding the 4 external relays expansion module allows using the 4 SPDT internal relays for pump alternation and the 4 SPST external relays for high, high-high, low, and low-low alarm indication.

\section*{Setting Up the Interlock Relay (Force On) Feature}

Relays 1-4 can be set up as interlock relays. To set up the relays for the interlock feature:
1. Access the Setup - Relay - Action menu and set the action to off.

2. In the Advanced features - User menu, program any of the digital inputs to Force On any of the internal relays (1-4). The Advanced Features Menu can be found on page 51.

3. Connect a switch or dry contact between the +5 V terminal and the corresponding digital input (dl- 1 to dl-4) terminal.


\section*{Interlock Relay Operation Example}

Relays 1 \& 2 are configured to energize (their front panel LEDs are off) when SW1 \& SW2 switches (above) are closed. If the contacts to these digital inputs are opened, the corresponding front panel LEDs flash, indicating this condition. The processes being controlled by the interlock relay will stop, and will re-start only after the interlock relay is re-activated by the digital inputs (switches).
Note: If multiple digital inputs are assigned to the same relay, then the corresponding logic is (AND) - i.e. both switches must be closed to trip the relay.

\section*{Scaling the 4-20 mA Analog Output (Rout)}

The 4-20 mA analog outputs can be scaled to provide a 4-20 mA signal for any display range selected. The Analog Outputs can be mapped to PVs or Math Channels. To select the channel and source assignments the analog outputs are assigned to, see Analog Output Source Programming on page 64.
No equipment is needed to scale the analog outputs; simply program the display values to the corresponding mA output signal.
The Analog Output menu is used to program the 4-20 mA outputs based on display values.


There are three analog outputs available. These only display when they are enabled. See graphic below.


Notes: Changes to the settings are saved to memory only after pressing ENTER. Changes made to settings prior to pressing ENTER are not saved. Once ENTER is pressed, the display moves to the next menu.

\section*{Setting Up the Password (PR55)}

The Password menu is used for programming three levels of security to prevent unauthorized changes to the programmed parameter settings.

Pass 1: Allows use of function keys and digital inputs
Pass 2: Allows use of function keys, digital inputs and editing set/reset points
Pass 3: Restricts all programming, function keys, and digital inputs.

\section*{Protecting or Locking the Scanner}

Enter the Password menu and program a six-digit password.


\section*{Making Changes to a Password Protected Scanner}

If the scanner is password protected, the scanner will display the message Locd (Locked) when the Menu button is pressed. Press the Enter button while the message is being displayed and enter the correct password to gain access to the menu. After exiting the programming mode, the scanner returns to its password protected condition.

\section*{Disabling Password Protection}

To disable the password protection, access the Password menu and enter the correct password twice, as shown below. The scanner is now unprotected until a new password is entered.


If the correct six-digit password is entered, the scanner displays the message unLoc (Unlocked) and the protection is disabled until a new password is programmed.
If the password entered is incorrect, the scanner displays the message Locd (Locked) for about two seconds, and then it returns to Run Mode. To try again, press Enter while the Locked message is displayed.

Did you forget the password?
The password may be disabled by entering a master password once. If you are authorized to make changes, enter the master password 508655 to unlock the scanner.

\section*{Advanced Features Menu}

To simplify the setup process, functions not needed for most applications are located in the Advanced Features menu:
1. Scan Mode: Auto or manual; Go on alarm or stop on alarm
2. Control relays and analog output
3. Noise Filter
4. Noise Filter Bypass
5. Rounding Feature
6. Select Math, Linearization function, Cutoff
7. User Programming for function keys and digital I/O
8. Copy Feature
9. System Information


\section*{Advanced Menu Navigation Tips:}
- Press and hold the Menu button for three seconds to access the Advanced Features Menu.
- Press the Up arrow button to scroll through the Advanced Features Menu.
- Press Menu at any time, to exit and return to Run mode.
- Changes made to settings prior to pressing Enter/Scan are not saved.
- Changes to the settings are saved to memory only after pressing Enter/Scan.
- The display automatically moves to the next menu every time a setting is accepted by pressing Enter/Scan.

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Advanced Features Menu \& Display Messages
\begin{tabular}{|c|c|c|c|c|c|}
\hline Display & Parameter & Action/Setting & Display & Parameter & Action/Setting \\
\hline SLRn & Scan & Enter Scan menu & \multirow[t]{2}{*}{no PtS} & \multirow[t]{2}{*}{Number of Points} & \multirow[t]{2}{*}{Enter Number of Linearization Points} \\
\hline ก odE & Scan Mode & Select Auto or Manual & & & \\
\hline & & Scan Mode & \multirow[t]{2}{*}{SLRLE} & \multirow[t]{2}{*}{Scale} & \multirow[t]{2}{*}{Scale Number of Linearization Points} \\
\hline \multirow[t]{2}{*}{Ruto} & \multirow[t]{2}{*}{Automatic} & \multirow[t]{2}{*}{Select Automatic Scan Mode} & & & \\
\hline & & & inP 1 & Input 1 & Program input 1 value \\
\hline Lime & Scan Time & Select Scanning Time & d. 5 ' & Display 1 & Program display 1 value \\
\hline ก 8 R & Manual & Select Manual Scan Mode & inip 2 & Input 2 & Program input 2 value (up to 32 points for PV1 \& PV2 \\
\hline RLRR「年 & Alarm & Select Go or Stop Alarm & \multirow[t]{2}{*}{d.5 2} & \multirow[t]{2}{*}{Display 2} & \multirow[t]{2}{*}{Program display 2 value (up to 32 points for PV1 \& PV2)} \\
\hline 50 & Go & Select Alarm Go & & & \\
\hline Stop & Stop & Select Alarm Stop & \multirow[t]{2}{*}{59ıRrE} & \multirow[t]{2}{*}{Square Root} & \multirow[t]{2}{*}{Enter Square Root menu} \\
\hline \multirow[t]{2}{*}{Contri} & \multirow[t]{2}{*}{Control} & \multirow[t]{2}{*}{Enter Control menu for relays and analog output 1} & & & \\
\hline & & & Prout \(E\) & Programmable Exponent & Enter Programmable Exponent menu \\
\hline Ruto & Automatic & Select Automatic Control of Outputs and Relays & 65000 & Programmable Exponent Value & Enter the Programmable Exponent Value \\
\hline n & Manual & Select Manual Control of Outputs and Relays & rht & Round Horizontal Tank & Enter Round Horizontal Tank menu \\
\hline Rout i & Analog Output 1 & Select Analog Output 1 for manual control & inch & Inch & Enter to calculate tank values in Inches \\
\hline riy & Relay 1 & Select Relay 1-8 for manual control & cกา & Centimeters & Enter to calculate tank values in Centimeters \\
\hline on & On & Select On for Relay 1-8 & dinio r & Diameter & Enter tank diameter \\
\hline ofF & Off & Select Off for Relay 1-8 & LEnuth & Length & Enter tank length \\
\hline FiteEr & Filter & Enter Filter menu & n \({ }^{\text {ath }}\) & Math & Enter Math menu \\
\hline Pu i & PV 1 Filter & Program Filter Value for PV 1 & [h [:* & Channel C1 & *Enter Math Channel C1-C4 menu \\
\hline PU & PV 2 Filter & Program Filter Value for PV 2 & gipertn & Operation & Enter Math Operation menu \\
\hline 6SPR55 & Filter Bypass & Enter Filter Bypass menu & Con5t & Constant & Enter Math Constant menu \\
\hline PU & PV 1 Filter Bypass & Program Filter Bypass Value for PV 1 & RodEr & Adder & Enter Adder Value \\
\hline PU 2 & PV 2 Filter & Program Filter Bypass & FRELr & Factor & Enter Factor Value \\
\hline & Bypass & Value for PV 2 & Sunา & Sum & Math Function Sum \\
\hline round & Rounding Feature & Enter Rounding Feature menu & d \({ }^{\text {d }}\) & Difference & Math Function Difference \\
\hline \multirow[t]{3}{*}{!*} & \multirow[t]{3}{*}{1 Rounding Value} & Program Rounding Value for PV & d.FRb5 & Absolute Difference & Math Function Absolute Difference \\
\hline & & \multirow[t]{2}{*}{*(User-selectable \& rounds to the nearest 1 , \(2,5,10,20,50,100\) )} & Rut & Average & Math Function Average \\
\hline & & & กา uit & Multiply & Math Function Multiply \\
\hline SELEct & Select & Enter Select menu & d \({ }^{\text {d }}\) dE & Divide & Math Function Divide \\
\hline Functo & Function & Enter data Linearization Function menu & H,-PU & Max & Math Function Maximum of all selected PVs \\
\hline \multirow[t]{2}{*}{PU :*} & \multirow[t]{2}{*}{PV 1 Function} & \multirow[t]{2}{*}{*Enter Linearization Function menu for all enabled PVs} & Lo-PU & Min & Math Function Minimum of all selected PVs \\
\hline & & & drRus & Draw & Math Function Draw \\
\hline [h [ : \(*\) & Ch C1 Function & *Enter Linearization Function menu for all enabled math channels & usputu & Weighted Average & Math Function Weighted Average \\
\hline L MER & Linear & Enter Linear menu & rit io & Ratio & Math Function Ratio \\
\hline
\end{tabular}

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\begin{tabular}{|c|c|c|c|c|c|}
\hline Display & Parameter & Action/Setting & Display & Parameter & Action/Setting \\
\hline \multirow[t]{2}{*}{ConcEn} & \multirow[t]{2}{*}{Concentration} & \multirow[t]{2}{*}{Math Function Concentration} & PrEu & Previous & Previous PV \\
\hline & & & neht & Next & Next PV \\
\hline \multirow[t]{3}{*}{ח Rthe} & \multirow[t]{3}{*}{Math2} & \multirow[t]{3}{*}{Resultant Math Channel Math operation applied to other math channels (e.g. C3 = C1/C2)} & 5cRn & Scan & Scan or pause scan \\
\hline & & & Rich & Acknowledge & Acknowledge relays \\
\hline & & & rESEt & Reset & Enter Reset menu \\
\hline 5 ר\% & Sum & Math2 Function Sum & & & \\
\hline d, & Difference & Math2 Function Difference & ret Hi & Reset Max
Reset Min & Reset Maximum \\
\hline d.FRb5 & Absolute Difference & Math2 Function Absolute Difference & rSt HL & Reset Max-Min & Reset Maximum \& Minimum \\
\hline RUL & Average & Math2 Function Average & rELAS & Relay & Relay menu \\
\hline nา uit, & Multiply & Math2 Function Multiply & 5Et ** & Set Points 1-8 & Set Points 1-8 \\
\hline d 心 dE & Divide & Math2 Function Divide & \multirow[t]{2}{*}{riy d} & \multirow[t]{2}{*}{Relay Disable} & \multirow[t]{2}{*}{Relay Disable (all relays)} \\
\hline \multirow[t]{2}{*}{Cutoff} & \multirow[t]{2}{*}{Cutoff} & \multirow[t]{2}{*}{Enter Low Flow Cutoff menu} & & & \\
\hline & & & riy E & Relay Enable & Relay Enable (all relays) \\
\hline \multirow[t]{2}{*}{Pu} & \multirow[t]{2}{*}{PV 1 Cutoff} & \multirow[t]{2}{*}{Program Cutoff Value for PV 1} & 0 Hold & Output Hold & Output Hold (all relays) \\
\hline & & & \multirow[t]{2}{*}{d HoLd} & \multirow[t]{2}{*}{Display Hold} & \multirow[t]{2}{*}{Display Hold (while held low)} \\
\hline \multirow[t]{2}{*}{Pu} & \multirow[t]{2}{*}{PV 2 Cutoff} & \multirow[t]{2}{*}{Program Cutoff Value for PV 2} & & & \\
\hline & & & d.5RbL & Disable & Disable \\
\hline \multirow[t]{2}{*}{RoutPr} & \multirow[t]{2}{*}{Analog Output Program} & \multirow[t]{2}{*}{Enter Analog Output Programmable parameters menu} & Contri & Control & Control menu \\
\hline & & & di t* & DI 1-8 & *Digital Inputs 1-8 \\
\hline Rout 1* & Analog Output 1-3 & *Analog Output 1-3 (If Installed) & \% Enu & Menu & Menu \\
\hline \multirow[t]{2}{*}{Sour [E} & \multirow[t]{2}{*}{Analog Output Data Source} & \multirow[t]{2}{*}{Enter Analog Output Data Source menu} & r wht & Right & Right \\
\hline & & & \({ }^{\circ} \mathrm{P}\) & Up & Up \\
\hline \multirow[t]{2}{*}{PU \%} & \multirow[t]{2}{*}{Source PV} & \multirow[t]{2}{*}{*Select PV for Analog Output Data Source} & EntEr & Enter & Enter \\
\hline & & & \multirow[t]{2}{*}{\(F\) on t*} & \multirow[t]{2}{*}{Force On Relay 1} & \multirow[t]{2}{*}{*Force On Relay 1-4} \\
\hline \multirow[t]{2}{*}{Ch [:*} & \multirow[t]{2}{*}{Source Math Channel} & \multirow[t]{2}{*}{*Select C1-4 for Analog Output Data Source} & & & \\
\hline & & & d0 1* & DO 1-8 & *Digital Outputs 1-8 \\
\hline 5Et i* & Set Point 1-8 & *Select Set Points 1-8 & RLT & Alarm 1-8 & *Alarm 1-8 \\
\hline \multirow[t]{2}{*}{brERH} & \multirow[t]{2}{*}{Communication s Break} & \multirow[t]{2}{*}{Enter the Analog Output value when Communications Break is detected} & Rch & Acknowledge & Acknowledge \\
\hline & & & re5Et & Reset & Enter Reset menu \\
\hline \multirow[t]{2}{*}{UnorE} & \multirow[b]{2}{*}{Ignore Break} & \multirow[b]{2}{*}{Ignore Break} & r \(5 t \mathrm{H}\), & Reset Max & Reset Maximum \\
\hline & & & \multirow[t]{2}{*}{r5t Lo} & \multirow[t]{2}{*}{Reset Min} & Reset Minimum \\
\hline ForcE & Force Break & Force Break & & & \multirow[t]{2}{*}{Reset Maximum \& Minimum} \\
\hline [RL ib & Calibration & Enter the Analog Output Calibration menu & rSt HL & Reset Max-Min & \\
\hline \multirow[t]{2}{*}{ת 8 HH} & \multirow[t]{2}{*}{Maximum} & \multirow[t]{2}{*}{Select Maximum value for all Analog Outputs} & d 5RbL & Disable & Disable \\
\hline & & & dind & Diagnostic & Enter Diagnostics menu \\
\hline กา & Minimum & Select Minimum value for all Analog Outputs & rE5Et & Reset & Reset to Factory Defaults \\
\hline 0-rRnE & Overrange & Enter the Analog Output value for an Overrange condition & LEd \(t\) & LED Test & LEDs cycle through all digits, decimal points, and indicators \\
\hline \multirow[t]{2}{*}{U-rRnu} & \multirow[t]{2}{*}{Underrange} & \multirow[t]{2}{*}{Enter the Analog Output value for an Underrange condition} & info & Info & Displays Scanner information \\
\hline & & & \multirow[t]{2}{*}{5 Ft} & \multirow[t]{2}{*}{Software} & \multirow[t]{2}{*}{Displays Software information} \\
\hline \multirow[t]{2}{*}{\({ }_{\text {uSEr }}\)} & \multirow[t]{2}{*}{User} & \multirow[t]{2}{*}{Enter the User menu for assigning function keys and digital I/O} & & & \\
\hline & & & UEr & Software Version & Displays Software Version information \\
\hline
\end{tabular}

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\section*{Scan Function (5[Rn)}

The Scan menu is used to program the PV scan mode and the scanner's behavior on alarm condition. The operator is able to scan automatically based on a time parameter, or scan manually with front panel keys or digital inputs. The operator is also able to set the scanner to stop on alarm or continue scanning on alarm. To resume scanning the operator must press the Next or Previous button. Please follow the menu below for details. In the Stop on Alarm mode, the scanner will go to the alarmed PV and remain there until the operator manually advances to the next PV or returns to the previous PV. If a new alarm is detected the process is repeated. The scanner ignores old alarms.


\section*{Control Menu (LontrL)}

The Control menu is used to control the 4-20 mA analog output and the relays manually, ignoring the input. Each relay and analog output can be programmed independently for manual control. Selecting automatic control sets all relays and analog output for automatic operation.


\section*{Noise Filter (F LLEEr)}

Most applications do not require changing this parameter. It is intended to help attain a steady display with unsteady (noisy) input data. The field selectable noise filter averages any minor or quick changes in the input data and displays the reading with greater stability. Increasing the filter value will help stabilize the display. However, this will reduce the display response to changes on the input data. The filter level may be set anywhere from 2 to 199. Setting the filter value to zero disables the filter function, and the bypass setting becomes irrelevant.


\section*{Noise Filter Bypass (bYPR55)}

The scanner can be programmed to filter small input changes, but allow larger input changes to be displayed immediately, by setting the bypass value accordingly. If the input signal goes beyond the bypass value, it will be displayed immediately with no averaging done on it. The noise filter bypass value may be set anywhere from 0.2 to 99.9. Increasing the bypass value may slow down the display response to changes on the input signal.


\section*{Rounding Feature (round)}

The rounding feature is used to give the user a steadier display with fluctuating signals. Rounding is used in addition to the filter function. Rounding causes the display to round to the nearest value according to the rounding criteria selected by the user. This setting affects the last three digits, regardless of decimal point position.

\section*{Select Menu (5ELEct)}

The Select menu is used to select the input data linearization function (linear, square root, programmable exponent, or round horizontal tank), math functions, constants, low-flow cutoff, and analog output programming. Multi-point linearization is part of the linear function selection.


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Input Data Conditioning Function Menu (Functn)
The Function menu is used to select the input-to-output transfer function applied to the input data: linear, square root, programmable exponent, or round horizontal tank volume calculation. Multi-point linearization (for PV1 and PV2) is part of the linear function selection. Scanners are set up at the factory for linear function with 2-point linearization. The linear function provides a display that is linear with respect to the input data (e.g \(0.000=0.000,10.000=10.000\), and then \(5.000=5.000\) ).


\section*{Linear Function Menu ( \(L\) inERr)}

Scanners are set up at the factory for linear function with 2-point linearization. Up to 32 linearization points can be selected for PV1 and PV2 under the Linear function in the Advanced Features menu. The multi-point linearization can be used to linearize the display for non-linear signals such as those from level transmitters used to measure volume in odd-shaped tanks or to convert level to flow using weirs and flumes with complex exponents.
Note: Multi-point Linearization applies to PV1 and PV2 only. All other PVs use two linearization points.


\section*{Square Root Function Menu (59uRrE)}

The square root function is used to calculate flow measured with a differential pressure transmitter. The flow rate is proportional to the square root of the differential pressure. Scale the scanner so that the low input signal (e.g. 4 mA ) is equal to zero flow and the high input signal (e.g. 20 mA ) is equal to the maximum flow.


\section*{Programmable Exponent Function Menu (Pro[E)}

The programmable exponent function is used to calculate open-channel flow measured with a level transmitter in weirs and flumes. The flow rate is proportional to the head height. Scale the scanner so that the low input signal (e.g. 4 mA ) is equal to zero flow and the high input signal (e.g. 20 mA ) is equal to the maximum flow. This method works well for all weirs and flumes that have a simple exponent in the flow calculation formula. For weirs and flumes with complex exponents it is necessary to use a strapping table and the 32-point linearization of the scanner.


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Round Horizontal Tank Function Menu (rht)
This function is used to calculate volume in a round horizontal tank with flat ends. The volume is calculated based on the diameter and length of the tank. The tank's dimensions can be entered in inches or centimeters; the scanner automatically calculates the volume in gallons or liters. After entering the dimensions, complete the scaling process with the display values calculated by the scanner. The scanner can be re-scaled to display the volume in any engineering unit without the need to reenter the dimensions again.

\section*{Changing the Volume from Gallons to Liters}

In the above graphic, entering the 48 " for the diameter and 120 " for the length of the round horizontal tank, the scanner automatically calculates that the volume of the tank is 940.02 gallons.
1. Convert gallons to liters

1 US gallon \(=3.7854 \mathrm{~L}\)
\(940.02 \mathrm{gal}=3558.4 \mathrm{~L}\)
2. Go to the Setup - PV - Decimal Point menu and change the decimal point to 1 decimal.
3. Go to the Setup - PV-Scale menu and press Enter untild 152 is shown on line 1 .
4. Press Enter and change the display 2 value to 3558.4.
5. The scanner is now displaying the volume in liters. Note: The display can be scaled to display the volume in any engineering units.


\section*{Math Functions (ר Rth)}

The Math menu is used to select the math function that will determine the channels \(\mathrm{C} 1-\mathrm{C} 4\) value. These math functions are applied to PVs and other math channels. The results are displayed by selecting Display Channel C (d [h [) in the Display menu. Most math functions may be applied to all PVs: For example, it is possible to add up to 16 PVs and calculate the total volume of all the tanks in a field. The Math2 function allows for further calculations on the results of other math channels (e.g. \(\mathrm{C} 4=\mathrm{C} 2 / \mathrm{C} 1\) ). The following math functions are available:
\begin{tabular}{|c|c|c|}
\hline Name & Math Operation (Examples) ( \(\mathrm{P}=\) Adder, \(\mathrm{F}=\) Factor) & Setting \\
\hline Addition & (PV1+PV2+P)*F & 5 ¢ \\
\hline Difference & (PV1-PV2+P)*F & d, 1 \\
\hline Absolute difference & ((Abs(PV1-PV2)+P)*F & d, FRb5 \\
\hline Average & (((PV1+PV2)/2)+P)*F & Rutis \\
\hline Multiplication & \(((\mathrm{PV} 1 * \mathrm{PV} 2)+\mathrm{P})^{*} \mathrm{~F}\) & mevit \\
\hline Division & \(((\mathrm{PV} 1 / \mathrm{PV} 2)+\mathrm{P})^{*} \mathrm{~F}\) & dUdE \\
\hline Max PV & Max value of all selected PV s & H,-PU \\
\hline Min PV & Min value of all selected PVs & Lo-PU \\
\hline Draw & ((PV1/PV2)-1)*F & drRus \\
\hline Weighted average & ((PV2-PV1)*F)+PV1 & u-RULE \\
\hline Ratio & (PV1/PV2)*F & rat io \\
\hline Concentration & (PV1/(PV1+PV2))*F & ConcEn \\
\hline Math 2 & Math on other math channels & monthe \\
\hline Addition & \(\mathrm{C} 3=(\mathrm{C} 1+\mathrm{C} 2+\mathrm{P})^{*} \mathrm{~F}\) & 5 บกา \\
\hline Difference & \(\mathrm{C} 4=(\mathrm{C} 1-\mathrm{C} 2+\mathrm{P})^{*} \mathrm{~F}\) & d \({ }^{\text {F }}\) \\
\hline Absolute difference & \(\mathrm{C} 3=\left((\mathrm{Abs}(\mathrm{C} 1-\mathrm{C} 2)+\mathrm{P})^{*} \mathrm{~F}\right.\) & difRb5 \\
\hline Average & \(\mathrm{C} 4=((\) C1 \(+\mathrm{C} 2) / 2)+\mathrm{P})^{*} \mathrm{~F}\) & Rilu \\
\hline Multiplication & \(\mathrm{C} 3=\left(\left(\mathrm{C} 1^{*} \mathrm{C} 2\right)+\mathrm{P}\right)^{*} \mathrm{~F}\) & moult \\
\hline Division & \(\mathrm{C} 4=((\mathrm{C} 1 / \mathrm{C} 2)+\mathrm{P})^{*} \mathrm{~F}\) & did dE \\
\hline
\end{tabular}

\section*{Math Constants (Con5t)}

The Math Constants menu is used to set the constants used in the math channel. The math functions include the selected PVs, as well as the constants P (Adder) and the Factor F (Multiplier) as indicated in the above examples.
The Adder constant ( P ) may be set from -99.999 to 999.999.
The Factor constant (F) may be set from 0.001 to 999.999.
The above chart details the math functions that may be selected in the Math Function menu.

Math Function Menu (n Rth)


Notes:
1. In the above menu, "A" \& " \(B\) " in equations can represent any PVs (PV1-PV16). See table above.
2. Each digit represents one PV in hexadecimal format, except PV16 (G).
3. PV1-PV9 = 1-9, PV10-PV16 = A-G
4. No PV selected = "underscore symbol"
5. Digit range: \(1-\mathrm{G}\), then " ""
6. If there is an empty digit, the scanner will end the equation at that point.
7. For Math2 Channel, "C" is fixed, indicating which Math Channels are being processed.
8. Please refer to the following graphics for details on various Math Functions:



\section*{Draw Menu (drRus)}

Only two PVs at a time will be used for this function.


Notes:
1. Press Up arrow to scroll through PV1 - PV16
2. The first \(P V\) is the dividend and the second PV is the divisor.

\section*{Ratio Menu (rRt io)}

Only two PVs at a time will be used for this function


Notes:
1. Press Up arrow to scroll through PV1 - PV16 2. The first \(P V\) is the dividend and the second \(\square\) PV is the divisor.

Minimum PV Menu (Lo-Pu)


Only two PVs at a time will be used for this function


Notes:
1. Press Up arrow to scroll through PV1 - PV16
2. The first PV selected is the first PV in the equation.

\section*{Concentration Menu ([ancEn)}

Only two PVs at a time will be used for this function


PU 2
ConcEn


Notes:
1. Press Up arrow to scroll through PV1 - PV16
2. The first PV is the dividend and the Sum of \(\square\) the PVs is the divisor.

\section*{Low-Flow Cutoff (CutoFF)}

The low-flow cutoff feature allows the scanner to be programmed so that the often unsteady output from a differential pressure transmitter, at low flow rates, always displays zero on the scanner. The cutoff value may be programmed from 0 to 999999 . When the input data is below the cutoff value, the scanner will display zero. Programming the cutoff value to zero disables the cutoff feature.


\section*{Analog Output Source Programming (RoutPr)}

The 4-20 mA analog outputs can be programmed for source of data, overrange and underrange, absolute maximum and minimum output, and communications break values. They can also be recalibrated.

- To calibrate the analog outputs, follow the graphic above while measuring the mA output signal.
- The overrange and underrange values are the values that will be output when the display shows an overrange or underrange condition. This setting is common to all analog outputs.
- The maximum and minimum values are the absolute limits for the \(4-20 \mathrm{~mA}\) output. This setting is common to all analog outputs.
- The communications break value determines the mA output when a Slave fails to reply to a command within the Response time.

\section*{User Menu (u5Er)}

The User menu allows the user to assign the front panel function keys F1, F2, and F3, the digital input F4 (a digital input located on the signal input connector), and up to eight additional digital inputs to access most of the menus or to activate certain functions immediately (e.g. reset max \& min, hold relay states, etc.). This allows the meter to be greatly customized for use in specialized applications.

Up to eight digital outputs can be assigned to a number of actions and functions executed by the meter (i.e. alarms, relay acknowledgement, reset max, min, or max \& min, tare, and reset tare). The digital outputs can be used to trigger external alarms or lights to indicate these specific events.


Function Keys \& Digital I/O Available Settings
\begin{tabular}{|c|c|}
\hline Display & Description \\
\hline \(5[\) nn & Scan PVs \\
\hline nEHt & Next PV \\
\hline Preu & Previous PV \\
\hline R. \({ }^{\text {r }}\) & Acknowledge all active relays that are in a manual operation mode such as auto-manual or latching \\
\hline re5Et & Directly access the reset menu \\
\hline r \(5 t \mathrm{H}\) & Reset the stored maximum display values for all channels \\
\hline r5t Lo & Reset the stored minimum display values for all channels \\
\hline r \(5 t \mathrm{HL}\) & Reset the stored maximum \& minimum display values for all channels \\
\hline rELRS & Directly access the relay menu \\
\hline SEt 1* & Directly access the set point menu for relay 1 (*through 8) \\
\hline rly d & Disable all relays until a button assigned to enable relays (rLYE) is pressed \\
\hline rLy E & Enable all relays to function as they have been programmed \\
\hline 5 HoLd & Hold current relay states and analog output as they are until a button assigned to enable relays ( \(\boldsymbol{L Y} \mathrm{E}\) ) is pressed \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Display & Description \\
\hline d HoLd & Hold the current display value, relay states, and analog output momentarily while the function key or digital input is active. The process value will continue to be calculated in the background. \\
\hline d.58bL & Disable the selected function key or digital I/O \\
\hline Contri & Directly access the control menu \\
\hline notnu & Mimic the menu button functionality (digital inputs only) \\
\hline r wht & Mimic the right arrow/F1 button functionality (digital inputs only) \\
\hline UP & Mimic the up arrow/F2 button functionality (digital inputs only) \\
\hline EntEr & Mimic the enter/F3 button functionality (digital inputs only) \\
\hline \(F\) on \({ }^{*}\) & Force relay 1 (*through 4) into the on state. This function is used in conjunction with a digital input expansion module to achieve interlock functionality. See page 48 for details about interlock relays. \\
\hline MLral \({ }^{\text {* }}\) & Provide indication when alarm 1 (*through 8) has been triggered (digital outputs only) \\
\hline
\end{tabular}

Digital Input Menu (dil)


\section*{Digital Output Menu (dD i)}


\section*{Reset Function (reset)}

The Reset function is used to reset the maximum or minimum reading (peak or valley) reached by the process; both may be reset at the same time by selecting "reset high \& low" ( \(\boldsymbol{r} 5 \mathrm{HL}\) H). This is applied to all PVs and math channels.

Resetting is possible by going into the USER menu, selecting a function key or digital input, pressing ENTER to take you to the next level, then pressing the Up arrow until you arrive at the RESET menu. Press ENTER to assign the RESET function to the selected function key or digital input. Now, when the scanner is in Run Mode, pressing the selected function key will take you to the RESET function, where you can scroll through Reset Hi (Max), Reset Lo (Min), and Reset HiLo (Reset Max and Min), choosing what value to reset. You can also select the specific reset function (e.g. Reset HiLo) to the selected digital input or function key.

\section*{4-20 mA Output Calibration}
- There is no need to recalibrate the \(4-20 \mathrm{~mA}\) output when first received from the factory.
- The 4-20 mA outputs is factory calibrated prior to shipment. The calibration equipment is certified to NIST standards.

The 4-20 mA output can be recalibrated in the field. A calibrated digital meter with an input range of at least 25 mA and a resolution of \(1 \mu \mathrm{~A}\) is recommended.

> CAUTION!
> neter or a meter with less resolution is used, th \(4-20 \mathrm{~mA}\) output could be adversely affected.

If an uncalibrated meter or a meter with less resolution is used, the calibration of the

\section*{4-20 mA Output Calibration Procedure}
1. Wire the DPM-100 4-20 mA output to a current loop that includes a power supply (internal or external 12 to 24 VDC), and the mA input on the digital meter. See page 17 for details.
2. Turn on all devices. Allow for a 15 to 30 minute warm-up.
3. Go to the Advanced Features menu, and navigate to the Analog Output Programming (RoutPr)/Calibration (CRL \(\boldsymbol{b}\) ) menu and press Enter.
4. The display will show 4 пาค. The DPM-100 mA output should now be close to 4 mA . Press Enter and the display will show \(\mathbf{0 4 . 0 0 0}\). Enter the actual value read by the digital mA meter and press Enter.
5. The display will show 20 nาค. The DPM- 100 mA output should now be close to 20 mA . Press Enter and the display will show 20.000. Enter the actual value read by the digital mA meter and press Enter.
6. The DPM-100 will now calculate the calibration factors and store them.
7. Press Menu to exit and return to Run mode.

\section*{DPM-100 Modbus \({ }^{\circledR}\) Display Instruction Manual}

\section*{Troubleshooting}

Due to the many features and functions of the scanner, it's possible that the setup of the scanner does not agree with what an operator expects to see. If the scanner is not working as expected, refer to the recommendations below.
\begin{tabular}{|c|c|}
\hline Symptom & Check/Action \\
\hline No display at all & Check power at power connector \\
\hline Not able to change setup or programming, Locd is displayed & Scanner is password-protected, enter correct six-digit password to unlock \\
\hline Scanner displays error message during scaling (Error) & Check: Input 2 must greater than Input 1, Input 3 must be greater than Input 2, etc. \\
\hline \begin{tabular}{l}
Scanner displays \\
1. 999999 \\
2. -99999
\end{tabular} & Indicating overrange or underrange condition Check the input data value and scaling in Setup menu \\
\hline Display stop scanning, ■LED indicator flashing & \begin{tabular}{l}
Check: \\
1. Stop on alarm feature has been enabled \\
2. Press PREV or NEXT to resume scanning
\end{tabular} \\
\hline Displays brERH message & \begin{tabular}{l}
Check: \\
1. RS-485 connection to slave devices \\
2. Slave Id, register number of slave devices \\
3. Baud rate and parity of all devices on the bus \\
4. Scanner Id must be different from other devices
\end{tabular} \\
\hline Snooper mode not reading the PVs on the RS-485 bus & \begin{tabular}{l}
Check: \\
1. Increase Master's Transmit Delay (e.g. Snooper delay \(=100 \mathrm{~ms}\), Master delay \(=110 \mathrm{~ms}\) ) \\
2. Increase Snooper's byte-to-byte timeout \\
3. Decrease the slave device's transmit delay to \(<10 \mathrm{~ms}\) \\
4. Snooper cannot read the same PV twice, check setup
\end{tabular} \\
\hline Scanner experiencing faults and communication breaks & \begin{tabular}{l}
Check: \\
Increase response time ( \(\mathbf{t}-\) rE5P) and/or transmit delay ( \(\operatorname{tr} \operatorname{diy}\) ). This may require some trial and error, as these are dependent upon the number of devices on the bus.
\end{tabular} \\
\hline Scanner not communicating with ScanView software & \begin{tabular}{l}
Check: \\
1. Serial adapter and cable \\
2. Serial settings \\
3. Scanner address, baud rate, and transmit delay
\end{tabular} \\
\hline Display does not respond to input data, reading a fixed number & \begin{tabular}{l}
Check: \\
Display assignment, it might be displaying max/ min
\end{tabular} \\
\hline Display reading is not accurate & \begin{tabular}{l}
Check: \\
1. PV Scaling \\
2. Check format selected: dec or ft\&in
\end{tabular} \\
\hline Relay operation is reversed & \begin{tabular}{l}
Check: \\
1. Fail-safe in Setup menu \\
2. Wiring of relay contacts
\end{tabular} \\
\hline Relay and status LED do not respond to signal & \begin{tabular}{l}
Check: \\
1. Relay action in Setup menu \\
2. Set and reset points
\end{tabular} \\
\hline Flashing relay status LEDs & Relays in manual control mode or relay interlock switches opened. \\
\hline If the display locks up or the scanner does not respond at all & Cycle the power to reboot the microprocessor. \\
\hline Other symptoms not described above & Call Technical Support for assistance. \\
\hline
\end{tabular}

\section*{Diagnostics Menu (d \(\mathrm{A}[\) )}

The Diagnostics menu is located in the Advanced Features menu, to access Diagnostics menu see page 51. This menu allows the user to test the functionality of all the meter LEDs, check the meter's software and version information, and erase the MeterView Pro software installation files from the meter. Press the Enter button to view the settings and the Menu button to exit at any time.

\section*{Determining Software Version}

To determine the software version of a scanner:
1. Go to the Diagnostics menu (d, RE) and press Enter button.
2. Press Up arrow button and scroll to Information menu ( inFo).
3. Press Enter to access the software number (5FE) and version (UEr) information. Write down the information as it is displayed. Continue pressing Enter until all the information is displayed.
4. The scanner returns to Run Mode after displaying all the settings.

\section*{Reset Scanner to Factory Defaults}

When the parameters have been changed in a way that is difficult to determine what's happening, it might be better to start the setup process from the factory defaults.

\section*{Instructions to load factory defaults:}
1. Enter the Advanced Features menu, see page 51.
2. Press Up arrow to go to Diagnostics menu
3. Press and hold Right arrow for three seconds, press Enter when display flashes rE5Et. Note: If Enter is not pressed within three seconds, the display returns to Run Mode.
4. The scanner goes through an initialization sequence (similar as on power-up), and loads the factory default settings.

\section*{Testing the Display LEDs}

Enter the Diagnostic menu and press the ENTER button to get to the LED Test menu (LEd \(\mathbf{t}\) ). Press the ENTER button to activate the LED Test. The DPM-100 will cycle through all digits, decimal points, and relay indicators to enable the operator to see that all are functioning properly. Press the ENTER button



\section*{DPM-100 Modbus \({ }^{\circledR}\) Display Instruction Manual}

\section*{Scanner Operation}

The DPM-100 scanner is capable of operating as a Modbus Master, Slave or Snooper. As a Slave, the DPM-100 requires connection to a Master device: PLC, DCS, etc. As a Master, the DPM-100 interfaces up to sixteen slave devices and can alternately display their Process Variables. As a Snooper it can be connected anywhere in the RS-485 bus to read any of the variables being requested by the Master device.

Four math channels (C1-C4) are available to perform operations on any PV or math channel, with adder and factor constants, and display the results. Engineering units or tags may be displayed with all PVs or math channels. Another level of Math functions can be performed on the resultant math channel Math2. For example, the operator can use the Math2 Channel to calculate the Sum of all other Math Channels, which may have each performed a different Math function.

The dual-line display can be customized by the user. Typically, the upper display is used to display the PV, while the lower display is used to display the tag for each PV.
Additionally, the scanner can be set up to display any input or math channel on the upper display and alternate between tag \& units on the lower display. The relays and analog output can be programmed to operate based on any PV or math channel.

\section*{Front Panel Buttons Operation}
\begin{tabular}{|c|c|}
\hline Button Symbol & Description \\
\hline \[
\underset{\text { MENU }}{\sim}
\] & Press to enter, exit Programming Mode, or exit max/min readings \\
\hline Prev F1 & Press to move to the previous PV or math channel \\
\hline \({ }_{\text {Next }}{ }^{\text {a }}\) & Press to move to the next PV or math channel \\
\hline \(\underset{\text { scan }}{\mathrm{Sc}^{\text {a }}}\) & Press once to pause scanning, press again to resume scanning \\
\hline
\end{tabular}

\section*{Function Keys Operation}

During operation, the programmable function keys operate according to the way they have been programmed in the Advanced Features - User menu.
The table above shows the factory default settings for F1, F2, and F3.

\section*{F4 Operation}

A digital input, F4, is standard on the scanner. This digital input is programmed identically to function keys F1, F2, and F3. The input is triggered with a contact closure to COM, or with an active low signal. During operation, F4 operates according to the way is has been programmed in the Advanced Features - User menu. See page 65 for details.

\section*{Maximum/Minimum Readings}

The max \& min readings (peak \& valley) reached by the PVs or math channels can be displayed by assigning the display to max/min through the Display Setup menu.
A digital input should be programmed to reset the max \& min readings.

\section*{Factory Defaults \& User Settings}

The following table shows the factory setting for most of the programmable parameters on the DPM-100 scanner.
\begin{tabular}{|c|c|c|c|c|c|}
\hline Parameter & Display & Default Setting & Parameter & Display & Default Setting \\
\hline Mode & nา odE & Master & \multirow[t]{2}{*}{Math, channel C1-4} & \multirow[t]{2}{*}{Sunา} & \multirow[t]{2}{*}{Sum} \\
\hline Function Code & Funiod & 03 & & & \\
\hline PV Number & Punbr & \begin{tabular}{l}
PV1-PV4 \\
Enabled
\end{tabular} & Adder (constant P) & RddEr & 0.000 \\
\hline Slave ID PV1-16 & SLRLS id & 001-016 & Factor (constant F) & FRictor & 1.000 \\
\hline Register & \multirow[t]{3}{*}{rEunbr} & \multirow[t]{3}{*}{40001} & & \multicolumn{2}{|l|}{F iLEEr} \\
\hline Number & & & Filter, PV 1 & PU & 0 \\
\hline PV1-16 & & & Filter, PV 2 & PU 2 & 0 \\
\hline \begin{tabular}{l}
Data Type \\
PV1-16
\end{tabular} & dRER & \multirow[t]{2}{*}{Float} & Bypass, PV 1 & L 4 PR55 & 0.2 \\
\hline & 1234 & & Bypass, PV 2 & b 4 PR55 & 0.2 \\
\hline Byte Order & 123 & Bi & Round & round & 1 \\
\hline Polling Time & t-PoLi & 5.0 second & Cutoff & \multicolumn{2}{|l|}{CutofF} \\
\hline \begin{tabular}{l}
Slave Response \\
Timeout
\end{tabular} & t-rESP & 10.0 second & \multirow[t]{2}{*}{Cutoff value, PV 1} & \multirow[t]{2}{*}{PU 1} & \multirow[t]{2}{*}{0.000 (disabled)} \\
\hline Serial & 5Er int & & & & \\
\hline Scanner ID & SLRn id & 246 & \multirow[t]{2}{*}{Cutoff value, PV 2} & \multirow[t]{2}{*}{PU} & \multirow[t]{2}{*}{0.000 (disabled)} \\
\hline Baud & bRud & 9600 & & & \\
\hline Parity & PRr ky & Even & Display assignment & d5PLRy & \\
\hline Byte-to-byte timeout & t-but & 0.01 second & Line 1 & dPU & Display PV \\
\hline Setup & \multicolumn{2}{|l|}{5EtuP} & Line 2 & d LRL & Display tag \\
\hline Tag & ヒRL & \multirow[t]{2}{*}{PV 1 - PV 16} & Display intensity & d-inty & 8 \\
\hline PV1-16 & PU: & & Relay 1 assignment & Pu i & PV 1 \\
\hline Units PV1-16 & \[
\begin{aligned}
& \text { Lin it5 } \\
& \text { Pu: }
\end{aligned}
\] & FEET & Relay 1 action & Rct 1 & Automatic \\
\hline Units C1-4 & \[
\begin{aligned}
& \text { Lin it5 } \\
& \text { Ch Ei }
\end{aligned}
\] & UnitC1 - UnitC4 & Relay 1 set point & 5Et 1 & 1.000 \\
\hline \begin{tabular}{l}
Display \\
Format PV1-16
\end{tabular} & Fornat PU: & Dec & Relay 1 reset point & r5t 1 & 0.500 \\
\hline \begin{tabular}{l}
Display \\
Format C1-4
\end{tabular} & Fornet [h [1 & Decimal & Relay 2 assignment & PU & PV 2 \\
\hline Display decimal & \multirow[t]{2}{*}{d.5P.dP} & \multirow[t]{2}{*}{ddd.ddd} & Relay 2 action & Rot ? & Automatic \\
\hline point & & & Relay 2 set point & 5Et 2 & 2.000 \\
\hline Float decimal point & FLot.dP & ddd.ddd & Relay 2 reset point & r5t 2 & 1.500 \\
\hline Number of points & no Pt5 & 2 (all PVs and C channels) & \multirow[t]{2}{*}{Relay 3 assignment} & \multirow[t]{2}{*}{PU} & \multirow[t]{2}{*}{PV 3} \\
\hline Scaling & \[
\begin{aligned}
& 5[R L E \\
& P_{U}, 1
\end{aligned}
\] & All & & & \\
\hline Input 1 & inp 1 & 0.000 & \multirow[t]{2}{*}{Relay 3 set point} & \multirow[t]{2}{*}{5Et 3} & \multirow[t]{2}{*}{3.000} \\
\hline Display 1 & d.5 1 & 0.000 & & & \\
\hline Input 2 & inp 2 & 10.000 & \multirow[t]{2}{*}{Relay 3 reset point} & \multirow[t]{2}{*}{r5t 3} & \multirow[t]{2}{*}{2.500} \\
\hline Display 2 & d.5 2 & 10.000 & & & \\
\hline
\end{tabular}

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\begin{tabular}{|c|c|c|c|c|c|}
\hline Parameter & Display & Default Setting & Parameter & Display & Default Setting \\
\hline Relay 4 assignment & PU 4 & PV 4 & Display 2 analog out & d.5 2 & 20.000 \\
\hline Relay 4 action & Rat 4 & Automatic & Output 2 value & Sut 2 & 20.000 mA \\
\hline Relay 4 set point & 5Et 4 & 4.000 & Source analog output & SourcE & PV 1 \\
\hline Relay 4 reset point & r5t 4 & 3.500 & Overrange output & B-rRniu & 21.000 mA \\
\hline Fail-safe relay 1 & FL5 1 & Off & \multirow[t]{2}{*}{Underrange output} & \multirow[t]{2}{*}{u-rRiúu} & \multirow[t]{2}{*}{3.000 mA} \\
\hline Fail-safe relay 2 & FL5 2 & Off & & & \\
\hline Fail-safe relay 3 & FL5 3 & Off & Comm. break output & brERH & 1.000 mA \\
\hline Fail-safe relay 4 & FL5 4 & Off & Maximum output & ר\% & 23.000 mA \\
\hline On delay relay 1 & On 1 & 0.0 sec & Minimum output & กา in & 1.000 mA \\
\hline Off delay relay 1 & AFF i & 0.0 sec & F1 function key & Fi & Previous PV \\
\hline On delay relay 2 & On 2 & \[
0.0 \mathrm{sec}
\] & F2 function key & \(F 2\) & Next PV \\
\hline Off delay relay 2 & OFF 2 & 0.0 sec & F3 function key & \(F 3\) & Scan/Pause \\
\hline On delay relay 3 & On 3 & 0.0 sec & \multirow[t]{2}{*}{F4 function (digital input)} & \multirow[t]{2}{*}{F4} & \multirow[t]{2}{*}{Acknowledge relays} \\
\hline Off delay relay 3 & OFF 3 & 0.0 sec & & & \\
\hline On delay relay 4 & Sn 4 & 0.0 sec & Digital input 1 & di 1 & Menu \\
\hline Off delay relay 4 & DFF 4 & 0.0 sec & Digital input 2 & di 2 & Right arrow \\
\hline Comm. break relay 1 & Bn & On & Digital input 3 & di 3 & Up arrow \\
\hline Comm. break & \multirow[t]{2}{*}{8 O} & \multirow[t]{2}{*}{On} & Digital input 4 & di 4 & Enter \\
\hline relay 2 & & & Digital output 1 & dil 1 & Alarm 1 \\
\hline Comm. break & \multirow[t]{2}{*}{80} & \multirow[t]{2}{*}{On} & Digital output 2 & dil 2 & Alarm 2 \\
\hline relay 3 & & & Digital output 3 & d0 3 & Alarm 3 \\
\hline Comm. break relay 4 & 8 B & On & Digital output 4 & d0 4 & Alarm 4 \\
\hline Display 1 analog & \multirow[t]{2}{*}{d 51} & \multirow[t]{2}{*}{4.000} & Password 1 & PR55 i & 000000 (unlocked) \\
\hline out & & & Password 2 & P955 2 & 000000 (unlocked) \\
\hline Output 1 value & Sut 1 & 4.000 mA & Password 3 & P955 3 & 000000 (unlocked) \\
\hline
\end{tabular}

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Division of Garner Industries

7201 N. 98th St. Lincoln, NE 68507
(402) 434-9102
www.binmaster.com Email: info@binmaster.com```


[^0]:    * Meter powered over USB for configuration only. Scanner will not read values from connected device while powered via USB connection.

